

Publications of the Intelligent Systems Division (Previously Robot Systems Division) Covering the Period January 1971 - April 1994

NIST

Debra L.F. Russell Intelligent Systems Division

NISTIR 5474

U.S. DEPARTMENT OF COMMERCE Technology Administration National Institute of Standards and Technology Bldg. 220 Rm. B124 Gaithersburg, MD 20899



Publications of the Intelligent Systems Division (Previously Robot Systems Division) Covering the Period January 1971 - April 1994

Debra L.F. Russell Intelligent Systems Division

U.S. DEPARTMENT OF COMMERCE Technology Administration National Institute of Standards and Technology Bldg. 220 Rm. B124 Gaithersburg, MD 20899

July 1994



U.S. DEPARTMENT OF COMMERCE Ronald H. Brown, Secretary

TECHNOLOGY ADMINISTRATION
Mary L. Good, Under Secretary for Technology

NATIONAL INSTITUTE OF STANDARDS AND TECHNOLOGY Arati Prabhakar, Director



INTRODUCTION

This document consists of a list of publications by the staff of the Intelligent Systems Division, Manufacturing Engineering Laboratory (MEL), National Institute of Standards and Technology (NIST) for the period of January 1971 through April 1994.

Publications cover research done by the division in the areas of intelligent machines and systems, robotics, real-time sensory-interactive control, open-systems architectures, software development techniques, world modeling, construction, mining and automated manufacturing systems.

The division's functional statement is as follows:

Intelligent Systems Division (823): Strives to enhance U. S. Industrial competitiveness through the development and application of intelligent systems technologies; Develops and maintains competence in intelligent machines and systems, robotics, real-time sensory-interactive control, open-system architectures, software development techniques, simulation and modeling, and methods for intelligent system design and testing; Conducts research in techniques for planning and control, world modeling, sensory processing, and interactive graphics for operator interface; Works with industry, universities, and other government agencies to implement pre-commercial prototype, open-system architecture, intelligent control systems for a wide variety of applications; Applies artificial intelligence techniques to real-time sensory-interactive control for computerintegrated manufacturing systems; Supports other NIST laboratories and other government agencies in applications of intelligent systems with high national priority, such as construction, environmental clean-up, transportation systems, mining, and military applications; Develops reference model open-system architectures for intelligent control systems; Develops methodologies for design and implementation of intelligent control systems; Develops methods and tools for software development and testing; Develops and tests measures of performance for intelligent control systems, robots, and intelligent machines; Supports the development of new standards for intelligent machine systems, robots, and automated manufacturing systems.

Performance Measures (823.01): Performs research and development in robot performance characterization, measurement, and analysis; performance measurement standards; stabilized lifting platforms for positioning robots and tools; and robotic cranes for precise positioning of large objects.

Intelligent Controls Group (823.02): Performs research and develops methods for making machines behave intelligently which includes research in robotics, artificial intelligence, planning, task decomposition, servo control, world modeling, sensory processing, and related fields.

Systems Integration Group (823.03): Performs research on integrated robotic control systems for a wide variety of applications including intelligent manufacturing, highway transportation and military robotic programs including development of sensors, off-line programming techniques, sensor-based automatic measurement and control techniques, standard interfaces for subsystems and further adaptations of the NIST Real-time Control System (RCS) architecture.

Sensory Intelligence Group (823.04): Performs research in real-time, sensor-based control of intelligent machines including research topics such as robot vision, active and purposive vision, sensory data fusion, world modeling, real-time planning, mobility and navigation, and multisensor integration; develops methods for merging sensory information with prior knowledge for representing information about objects, states, space and time, and for generating intelligent action sequences in real-time.

Unmanned Systems Group (823.05): Performs research in intelligent machine control systems including semi-autonomous, autonomous, and remotely operated vehicles, as well as, other intelligent automated systems; develops system integration methods and standards for real-time intelligent machine systems; and develops simulation, modeling, and animation systems for evaluating the performance of intelligent machine systems and for visualizing operational scenarios.

The interested reader can obtain copies of publications from commercial publications sources such as the National Technical Information Service, university or reference libraries or from the Intelligent Systems Division.

To order publications from the Intelligent Systems Division, please send your request to:

National Institute of Standards and Technology Manufacturing Engineering Laboratory Intelligent Systems Division Building 220 Room B124 Gaithersburg, MD 20899

or fax to:

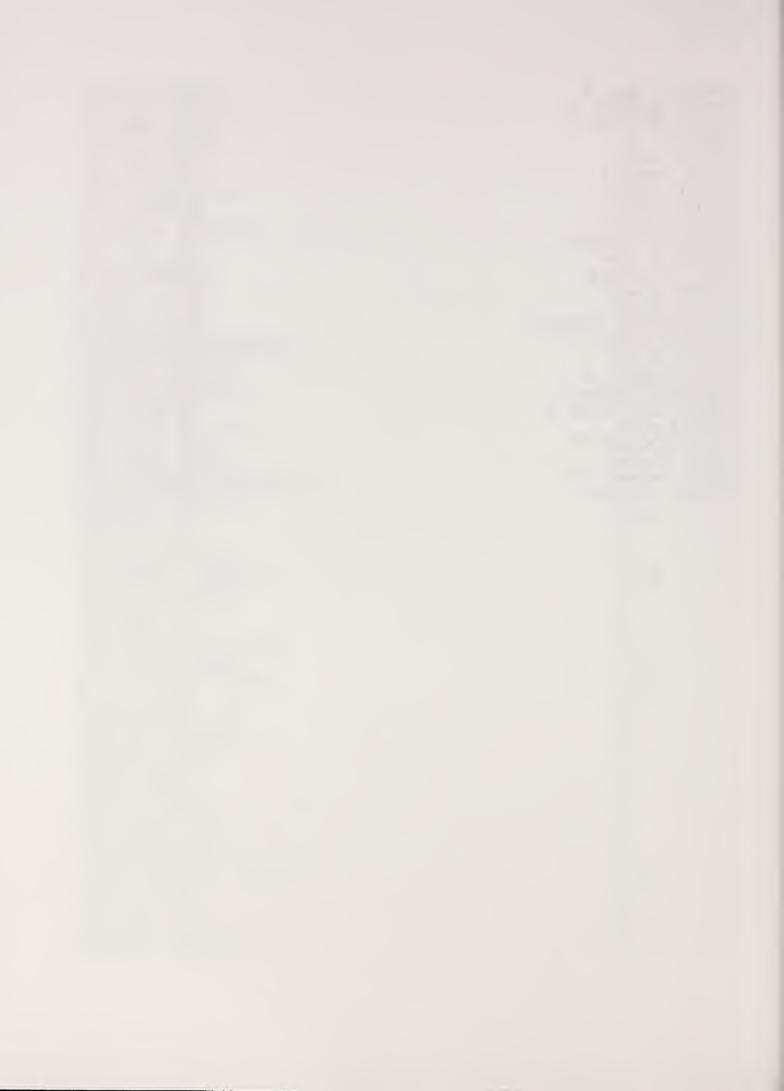
301-990-9688.

TABLE OF CONTENTS

| | PAGE NUMBER |
|---------------------------------------|----------------------|
| ABRISHAMIAN, A. | 1 |
| ALBUS, James S. | 1-8 |
| AMATUCCI, Edward | 8 |
| BARBERA, Anthony J. | 9-10 |
| BARKMEYER, Edward | 10 |
| BEUSAN, Sheri | 11 |
| BLIDBERG, D.R. | 11 |
| BLOODGOOD, John F. | 11 |
| BLOOM, Howard M. | 11 |
| · · · · · · · · · · · · · · · · · · · | 11-12 |
| BOSTELMAN, Roger V. | |
| BROWN, Christopher | 12 |
| BUNCH, Wayne R. | 12 |
| CHACONAS, Karen | 12-13 |
| CHELLAPPA, Rama | 13-14 |
| CLARK, Stephen N. | 14 |
| COOMBS, David | 14 |
| CORBETT, G.K. | 14 |
| DAGALAKIS, Nicholas G. | 15-16 |
| DAINIS, A. | 16 |
| DAMAZO, Brad | 16 |
| EVANS, John M. | 16 |
| FALCO, Joseph A. | 16 |
| FELDMAN, Philip | 16 |
| FIALA, John C. | 17-18 |
| FITZGERALD, M.L. | 18-19 |
| FORTMANN, T.E. | 19 |
| FRECHETTE, Simon | 20 |
| FURLANI, Cita M. | 20 |
| GOODWIN, Kenneth | 20 |
| HAAR, R. | 20 |
| HAYNES, Lenard S. | 20-21 |
| HENRICI, G.S. | 21 |
| HERMAN, Martin | 21-25 |
| HERRIMAN, M. | 25 |
| HIRA, Ron | $\frac{-25}{25}$ -26 |
| HOCKEN, Robert J. | 26 |
| HONG, Tsai-Hong | 26-28 |
| HORST, John A. | 28-29 |
| HUANG, Huang-Min | 29-30 |
| JACOFF, Adam | 30 |
| JOARDER, Kunal | 30 |
| JOHNSON, Tim L. | 30 |
| JONES, Albert | 30 |
| JUBERTS, Maris | 31 |
| KANADE, Takeo | 31 |
| KELMAR, Laura | 31-32 |
| KENT, Ernest W. | 32-33 |
| INDIANA, INTREST VV. | 34-33 |

| KILLOUGH, S.M. | 33 |
|------------------------|-------|
| KILMER, Roger D. | 33-34 |
| KRAMER, Thomas R. | 34 |
| KUROE, Shigeru | 35 |
| LAU, Herbert | 35 |
| | |
| LAU, Kam | 35 |
| LEAKE, Stephen A. | 35 |
| LEE, James D. | 35-36 |
| LEGOWIK, Steven A. | 36-37 |
| LI, W. X. | 37 |
| | |
| LIU, Hongche | 37 |
| LOWENFELD, E. | 37 |
| LUCK, R.L. | 37-38 |
| LUMIA, Ronald | 38-41 |
| LUPO, Jasper | 42 |
| | 42 |
| MANHEIMER, Kenneth L. | |
| MANSBACH, Peter | 42 |
| MCCAIN, Harry G. | 42-43 |
| MCLEAN, Charles R. | 43 |
| MEYSTEL, A. | 43 |
| MICHALOSKI, John L. | 44-45 |
| | |
| MILLIGAN S.D. | 45 |
| MITCHELL, Mary J. | 45 |
| MONTGOMERY, Raymond C. | 45 |
| MORRIS, Katherine C. | 45 |
| MURPHY, Karl N. | 45-46 |
| NAGALIA, S. | 47 |
| | |
| NAGEL, Roger N. | 47 |
| NASHMAN, Marilyn | 47-49 |
| NORCROSS, Richard J. | 49-50 |
| ORSER, Donald J. | 50 |
| OSKARD, David N. | 50 |
| | 50 |
| PALOMBO, L. | |
| PROCTOR, Frederick M. | 50-52 |
| QUINTERO, Richard | 52-53 |
| RANGACHAR, Ramesh | 53-54 |
| RAVIV, Daniel | 54-55 |
| RICHARDSON, B.S. | 56 |
| | |
| RIPPEY, William G. | 56 |
| ROBERTS, Karen J. | 56 |
| ROCHE, Martin | 56-57 |
| ROSOL, Mark | 57 |
| ROWE, Walter P. | 57 |
| RUSSELL, Robert T. | 57 |
| | |
| RUTOWSKI, W.S. | 57 |
| SAUDER, David A. | 57 |
| SCHNEIDERMAN, Henry W. | 57-58 |
| SCOTT, Harry A. | 58-59 |
| SENEHI, M.K. | 59 |
| SHAFFER, C.A. | 59 |
| CUNEIED Mishael O | |
| SHNEIER, Michael O. | 59-60 |
| SIEWERT, Thomas | 60 |
| | |

| SIMPSON, John A. | 61 |
|-----------------------|-------|
| SMITH, Bradford M. | 61 |
| STOUFFER, Keith A. | 61 |
| STROUSE, K. | 61 |
| SWETZ, Scott | 61 |
| SWYT, Dennis A. | 61 |
| SZABO, Sandor | 61-62 |
| TANGUY, Peter S. | 62-63 |
| TANIMOTO, S.L. | 63 |
| TARNOFF, Nicholas | 63 |
| TCHORYK, Peter | 63 |
| TSAI, Tsung-Ming | 63-64 |
| UNGER, Joseph | 64 |
| UZZAMAN, S. | 64 |
| VANDERBRUG, Gordon J. | 64 |
| WALKER, Ellen L. | 65 |
| WANG, Ben-Li | 65 |
| | |
| WARSAW, Barry A. | 65 |
| WAVERING, Albert J. | 66-67 |
| WHEATLEY, Thomas E. | 67-68 |
| YAKALI, H.H. | 68 |
| YANCEÝ, Charles W. | 68 |
| YANG, Charles | 68 |
| YANG, Jackson C.S. | 68-69 |
| YOUNG, Gin-Shu | 69 |
| TOUTO, GIII-BIIU | 0,7 |



Intelligent Systems Division (Previously Robot Systems Division) BIBLIOGRAPHY Lampary 1071 April 1004

January 1971 - April 1994

ABRISHAMIAN, A.

McCain, H.G., Kilmer, R.D., Szabo, S. and Abrishamian, A.

"Hierarchically Controlled Autonomous Robot for Heavy Payload Military Field Applications," Proceedings of the International Conference on Intelligent Autonomous Systems, Amsterdam, The Netherlands, December 1986

Dagalakis, N.G., Albus, J.S., Goodwin, K.R., Lee, J.D., Tsai, T.M., Abrishamian, A., Bostelman, R. and Yancey, C.

"Robot Crane Technology (Final Report)," NISTTN 1267, Gaithersburg, MD, July 1989

ALBUS, James S.

Albus, J.S.

"Theory of Cerebellar Function," Mathematical Biosciences 10 (1971) pgs 25-61

Albus, J.S.

"Theoretical and Experimental Aspects of a Cerebellar Model," Dissertation Abstracts International, Volume XXXIII, Number 12, 1973

Albus, J.S.

"Data Storage in the Cerebellar Model Articulation Controller (CMAC)¹," Transactions of the ASME Journal of Dynamic Systems, Measurement, and Control, September 1975

Albus, J.S.

"New Approach to Manipulator Control: The Cerebellar Model Articulation Controller (CMAC)¹," Transactions of the ASME Journal of Dynamic Systems, Measurement, and Control, September 1975

Evans, J.M. and Albus, J.S.

"Guidelines for the Design and Procurement of a Low Cost Mobile Robot," NBSIR 76-995, Gaithersburg, MD, December 1975

Albus, J.S.

"Hierarchical Interaction Between Behavior Generation and Pattern Recognition," Proceedings of the Automatic Image Pattern Recognition Symposium, May 1977

Evans, J.M., Albus, J.S. and Barbera, A.J.

"NBS/RIA Robotics Research Workshop," NBS Special Publication 500-29, Gaithersburg, MD, April 1978

Barbera, A.J., Albus, J.S. and Fitzgerald, M.L.

"Hierarchical Control of Robots using Microcomputers," Proceedings of the 9th International Symposium on Industrial Robots, Washington, DC, March 13-15, 1979

VanderBrug, G.J., Albus, J.S. and Barkmeyer, E.

"A Vision System for Real-Time Control of Robots," Proceedings of the 9th International Symposium on Industrial Robots, Washington, DC, March 13-15, 1979

Albus, J.S.

"A Model of the Brain for Robot Control Part 1: Defining Notation," Byte, pgs 10-32, June 1979

Albus, J.S.

"A Model of the Brain for Robot Control Part 2: A Neurologial Model," Byte, pgs 54-95, July 1979

Nagel, R.N., VanderBrug, G.J., Albus, J.S. and Lowenfeld, E.

"Experiments In Part Acquisition Using Robot Vision," Proceedings of the Autofact II, Robots IV Conference, Detroit, MI, October 29 - November 1, 1979

Albus, J.S.

"Mechanics of Planning and Problem Solving in the Brain," Mathematical Biosciences 45, pgs 247-293, 1979

Albus, J.S.

"ROBOT: An entry in Encyclopedia Americana," Encyclopedia Americana, 1979

Albus, **J.S.**, Barbera, A., Fitzgerald, M.L., Nagel, R., VanderBrug, G. and Wheatley, T.E. "A Measurement and Control Model for Adaptive Robots," Proceedings of the 10th International Symposium on Industrial Robots, Milan, Italy, March 1980

Albus, J.S., Barbera, A.J., Fitzgerald, M.L. and Nashman, M.

"Sensory Interactive," Robots 31st General Assembly of the International Institution for Production Engineering Research, Toronto, Canada, September 1, 1981

Albus, J.S., Barbera, A.J. and Nagel, R.N.

"Theory and Practice of Hierarchical Control," Proceedings of the 23rd IEEE Computer Society International Conference, Washington, DC, September 15-17, 1981

Smith, B.M., Albus, J.S. and Barbera, A.J.

"A Glossary of Terms for Robotics," NBSIR 81-2340, Gaithersburg, MD, October 1981

Barbera, A.J., Fitzgerald, M.L. and Albus, J.S.

"Concepts for a Real-Time Sensory-Interactive Control System Architecture," Proceedings of the Fourteenth Southeastern Symposium on System Theory, Blacksburg, VA, April 15-16, 1982

Albus, J.S., Kent, E., Nashman, M., Mansbach, P., Palombo, L. and Shneier, M.O. "Six-Dimensional Vision System." SPIE Vol 336 Robot Vision, May 1982

Shneier, M., Nagalia, S., Albus, J.S. and Haar, R.

"Visual Feedback for Robot Control," Proceedings of the International Workshop on Industrial Applications of Machine Vision, Research Triangle, NC, May 3-5, 1982

Albus, J.S.

"Research Topics in Industrial Robotics," Proceedings of the International Symposium on Industrial Robots, Paris, France, June 9-11, 1982

Albus, J.S., Mclean, C.R., Barbera, A.J. and Fitzgerald, M.L.

"Architecture for Real-Time Sensory-Interactive Control of Robots in a Manufacturing Facility," Proceedings of the Fourth IFAC/IFIP Symposium -- Information Control Problems in Manufacturing Technology, Gaithersburg, MD, October 26-28, 1982

Albus, J.S.

"Industrial Robot Technology and Productivity Improvement," Commissioned for Exloratory Workshop on the Social Impacts of Robotics: Summary and Issues, Congress of the U.S., OTA, Washington, DC, 1982

Simpson, J.A., Hocken, R.J. and Albus, J.S.

"Automated Manufacturing Research Facility of the National Bureau of Standards," Journal of Manufacturing Systems: Society of Manufacturing Engineers, 1(1): pgs 17-32, 1982

Albus, J.S., Mclean, C.R., Barbera, A.J. and Fitzgerald, M.L.

"Hierarchical Control for Robots in an Automated Factory," Proceedings of the 13th International Symposium on Industrial Robots/Robots 7, Chicago, IL, April 18-21, 1983

Kent, E.W. and Albus, J.S.

"Servoed World Models as Interfaces Between Robot Control Systems and Sensory Data," Robotica, Vol. 2, No. 1, pgs 17-25, January 1984

Barbera, A.J., Fitzgerald, M.L., Albus, J.S. and Haynes, L.S.

"Language Independent Superstructure for Implementing Real-Time Control Systems," Proceedings of the International Workshop on High-Level Computer Architecture, Los Angeles, CA, May 21-25, 1984

Albus, J.S., Barbera, A.J., Fitzgerald, M.L., Kent, E.W., Scott, H.A. and Kilmer, R.D. "A Control System for an Automated Manufacturing Research Facility," Proceedings of the Robots 8 Conference and Exposition, Volume 2 - Future Considerations, Detroit, MI, June 4-7, 1984

Barbera, A.J., Fitzgerald, M.L., Albus, J.S. and Haynes, L.S.

"RCS: The NBS Real-Time Control System," Proceedings of the Robots 8 Conference and Exposition, Volume 2 - Future Considerations, Detroit, MI, June 4-7, 1984

Albus, J.S.

"Robotics," Proceedings of NATO ASI Series, Vol. F11, Robotics and AI, Edited by M. Brady et al, Springer-Verlag Berlin Heidelberg, September 1984

Albus, J.S.

"Research Issues in Robotics," Society for the Advancement of Material and Process Engineering Conference (SAMPE), Albuquerque, NM, October 9, 1984

Haynes, L.S., Barbera, A.J., Albus, J.S., Fitzgerald, M.L. and McCain, H.G.

"Application Example of the NBS Robot Control System," Robotics and Computer Integrated Manufacturing, Vol. 1, No. 1, pgs 81-95, 1984

Fitzgerald, M.L., Barbera, A.J. and Albus, J.S.

"Real-Time Control Systems for Robots," 1985 SPI National Plastics Exposition Conference, McCormick Place, Chicago, IL, June 17-21, 1985

Albus, J.S., Mclean, C.R., Barbera, A.J. and Fitzgerald, M.L.

"Hierarchical Control for Robots and Teleoperators," Proceedings of the IEEE Workshop on Intelligent Control 1985, Rensselaer Polytechnic Institute, Albany, NY, August 1985

Albus, J.S.

"Robotics -- Past, Present, and Future," Proceedings of AGARD/NATO Consultant Mission on Robotics and Artificial Intelligence, September 26 - October 4, 1985

Albus, J.S.

"Trip Report: Japanese Progress in Robotics for Construction," Robotics Magazine, February 1986

Albus, J.S., Lumia, R. and McCain, H.G.

"Hierarchical Control of Intelligent Machines Applied to Space Station Telerobots," Proceedings of the 1987 IEEE International Symposium on Intelligent Control, Philadelphia, PA, January 19-20, 1987

Albus, J.S. and Blidberg, D.R.

"Control System Architecture for Multiple Autonomous Undersea Vehicles (MAUV)," Proceedings of the Fifth International Symposium on Unmanned, Untethered Submersible Technology, Merrimack, NH, June 22-24, 1987

Albus, J.S.

"Control System Architecture for Intelligent Machine Systems," Proceedings of the 1987 IEEE International Conference on Systems, Man and Cybernetics Conference, Alexandria, VA, October 20-23, 1987

Lumia, R. and Albus, J.S.

"Architecture to Support Teleoperation and Autonomy," Proceedings of the 1987 IEEE Conference on Systems, Man, and Cybernetics, Alexandria, VA, October 20-23,1987

Fiala, J.C., Lumia, R. and Albus, J.S.

"Servo Level Algorithms for the NASREM Telerobot Control System Architecture," SPIE Volume 851, Proceedings of SPIE 1987 Cambridge Symposium of Advances Intelligent Robotic Systems, Cambridge, MA, November 2-4, 1987

Herman, M. and Albus, J.S.

"Real-Time Hierarchical Planning for Multiple Mobile Robots," Proceedings of the DARPA Knowledge-Based Planning Workshop, Austin, TX, December 8-10, 1987

Dagalakis, N.G., Albus, J.S., Wang, B.L., Unger, J. and Lee, J.D.

"Stiffness Study of a Parallel Link Robot Crane for Shipbuilding Applications," Proceedings of the 7th International Conference for Offshore Mechanical and Arctic Engineering, Houston, TX, February 7-12, 1988

Albus, J.S., Dagalakis, N.G., Wang, B.L., Unger, J., Lee, J.D. and Yancey, C.W.

"Available Robotics Technology for Applications in Heavy Industry," 1988 Iron and Steel Exposition and Annual Convention, Houston, TX, February 7-12, 1988

Lumia, R. and Albus, J.S.

"Teleoperation and Autonomy for Space Robotics," Robotics, Vol. 4, No. 1, pgs 27-33, Elsevier Science Publishers B.V. (North-Holland), March 1988

Herman, M. and Albus, J.S.

"Overview of the Multiple Autonomous Underwater Vehicles (MAUV) Project," 1988 IEEE International Conference on Robotics and Automation, Philadelphia, PA, April 1988

Lee, J.D., Albus, J.S., Dagalakis, N.G. and Tsai, T.M.

"Computer Simulation of a Parallel Link Manipulator," Robotics and Computer Integrated Manufacturing, August 1988

Albus, J.S.

"System Description and Design Architecture for Multiple Autonomous Undersea Vehicles," NISTTN 1251, Gaithersburg, MD, September 1988

Lumia, R. and Albus, J.S.

"Space Robotics: Evolution and Applications," Paper Number 88-1640, Proceedings of the Instrument Society of America 88 International Conference, Houston, TX, October 16-21, 1988

Albus, J.S.

"The Central Nervous System as a Low and High Level Control System," NATO ASI Series, Vol. F43, 1988

Lee, J.D., Albus, J.S., Dagalakis, N.G. and Tsai, T.M.

"Performance Measures of a Robotic Micropositioner," Proceedings of the 2nd International Symposium on Robotics and Manufacturing ASME, pgs 1047-1056, 1988

Albus, J.S., McCain, H.G. and Lumia, R.

"NASA/NBS Standard Reference Model for Telerobot Control System Architecture (NASREM)," NISTTN 1235, 1989 Ed, Gaithersburg, MD, April 1989 (supersedes NBS Technical Note 1235, July 1987)

Albus, J.S.

"Marr and Albus Theories of the Cerebellum Two Early Models of Associative Memory," IEEE Compcon, May 1989

Albus, J.S., Quintero, R., Huang, H.M. and Roche, M.

"Mining Automation Real-Time Control System Architecture Standard Reference Model (MASREM)," NISTTN 1261, Volume 1, Gaithersburg, MD, May 1989

Albus, J.S.

"Control Architecture for Cooperative Intelligent Robots," Proceedings of Robots & Biological Systems Session, NATO Advanced Research Workshop, Il Ciocco, Tuscany, Italy, June 26-30, 1989

Dagalakis, N.G., Albus, J.S., Goodwin, K.R., Lee, J.D., Tsai, T.M., Abrishamian, A., Bostelman, R. and Yancey, C.

"Robot Crane Technology (Final Report)," NISTTN 1267, Gaithersburg, MD, July 1989

Albus, J.S., Lumia, R., Fiala, J. and Wavering, A.

"NASREM -- The NASA/NBS Standard Reference Model for Telerobot Control System Architecture," Proceedings of the 20th International Symposium on Industrial Robots, Tokyo, Japan, October 4-6, 1989

Albus, J.S., Quintero, R., Lumia, R., Herman, M., Kilmer, R. and Goodwin, K. "Concept for a Reference Model Architecture for Real-Time Intelligent Control Systems (ARTICS)," NISTTN 1277, Gaithersburg, MD, April 1990

Albus, J.S. and Hong, T.H.

"Motion, Depth, and Image Flow," Proceedings of 1990 IEEE International Conference on Robotics & Automation, Cincinnati, OH, May 13-18, 1990

Albus, J.S.

"Robotics: Where has it been? Where is it going?," International Journal of Robotics and Autonomous Systems, Vol. 6, No. 3, pgs 199-219, July 1990

Albus, J.S. and Quintero, R.

"Towards a Reference Model Architecture for Real-Time Intelligent Control Systems (ARTICS)," Proceedings of the IEEE Third International Symposium on Robotics and Manufacturing (ISRAM 90), Burnaby, British Columbia, Canada, July, 18-20,1990

Albus, J.S.

"Theory of Intelligent Systems," Fifth IEEE Symposium on Intelligent Control, Philadelphia, PA, September 5-7, 1990

Albus, J.S.

"Role of World Modeling and Value Judgment in Perception," Fifth IEEE Symposium on Intelligent Control, Philadelphia, PA, September 5-7, 1990

Albus, J.S.

"Hierarchical Interaction between Sensory Processing and World Modeling in Intelligent Systems," Fifth IEEE Symposium on Intelligent Control, Philadelphia, PA, September 5-7, 1990

Herman, M., Albus, J. and Hong, T.H.

"Real-Time Vision for Unmanned Vehicles," Proceedings of the Sensors Exposition, pgs 206c-1 to 206c-12, Chicago, IL, September 1990

Raviv, D. and Albus, J.S.

"Closed-form Massively-Parallel Range-from-Image Flow Algorithm," NISTIR 4450, Gaithersburg, MD, October 1990

Albus, J.S., Barkmeyer, E. and Jones, A.

"Approach to a System Architecture for Post Office Automation," Proceedings of the USPS 4th Advanced Technology Conference, Automation Technology Workshop, Washington, DC, November 5-7, 1990

Herman, M., Albus, J.S. and Hong, T.H.

"Intelligent Control for Multiple Autonomous Undersea Vehicles," Neural Networks for Control, Miller, W.T. and Sutton, R., Eds., MIT Press: Cambridge, MA, Fall 1990

Raviv, D. and Albus, J.S.

"Image-Flow Based Reconstruction Algorithm (Extracted from "Closed-Form Massively Parallel Range from Image Flow Algorithm")," Proceedings of the Fourth Annual Conference on Recent Advances in Robotics, Florida High-Technology and Industrial Council, Boca Raton, FL, May 16-17, 1991

Albus, J.S.

"Outline for a Theory of Intelligence," IEEE Transactions on Systems, Man and Cybernetics, Vol. 21, No. 3, pgs 473-509, May/June 1991

Huang, H.M., Quintero, R. and Albus, J.S.

"A Reference Model, Design Approach, and Development Illustration toward Hierarchical Real-Time System Control for Coal Mining Operations," Advances in Control & Dynamic Systems, Academic Press, July 1991

Albus, J.S., Quintero, R., Lumia, R., Herman, M., Kilmer, R. and Goodwin, K. "A Reference Model Architecture for ARTICS," ASME Manufacturing Review, Vol. 4, No. 3, September 1991

Herman, M., Albus, J.S. and Hong, T.H.

"Real-Time Vision for Autonomous and Teleoperated Control of Unmanned Vehicles," Active Perception and Robot Vision, Sood, A., ed., Springer-Verlag: Heidelberg, 1991

Albus, J.S.

"A Theory of Intelligent Machine Systems," Proceedings of IEEE Intelligent Robots and Systems '91 -- Intelligence for Mechanical Systems, Osaka, Japan, November 1991

Raviv, D. and Albus, J.S.

"Representations in Visual Motion," NISTIR 4747, Gaithersburg, MD, January 1992

Albus, J.S.

"A Canonical Architecture for Intelligent Machine Systems," Proceedings of Manufacturing International '92 Conference, Dallas, TX, March 29-April 1, 1992

Raviv, D. and Albus, J.S.

"A Closed-Form Massively-Parallel Range-From-Image-Flow Algorithm," Proceedings of the IEEE Transactions on Systems, Man and Cybernetics, Vol. 22, No. 2, March/April 1992

Raviv, D., Orser, D. and Albus, J.S.

"On Logarithmic Retinae," NISTIR 4807, Gaithersburg, MD, April 1992

Albus, J.S.

"RCS: A Reference Model Architecture for Intelligent Control," IEEE Journal on Computer Architectures for Intelligent Machines, May 1992

Albus, J.S., Juberts, M. and Szabo, S.

"RCS: A Reference Model Architecture for Intelligent Vehicle and Highway Systems," Proceedings of the 25th Silver Jubilee International Symposium on Automotive Technology and Automation, Florence, Italy, June 1-5, 1992

Albus, **J.S.**, Quintero, R., Proctor, F., Michaloski, J., Dagalakis, N. and Tarnoff, N. "NIST Support to the Next Generation Controller Program: 1991 Final Technical Report," NISTIR 4888, Gaithersburg, MD, August 1992

Albus, J.S., Bostelman, R.V. and Dagalakis, N.

"The NIST ROBOCRANE," Journal of Robotics System, Vol. 10, No. 5, pgs 709-724, Received March 3, 1992, accepted September 8, 1992

Albus, J.S.

"RCS: A Reference Model Architecture for Intelligent Machine Systems," Proceedings of the Workshop on Intelligent Autonomous Control Systems, Tel Aviv, Israel, November 1-3, 1992

Bostelman, R.V., Dagalakis, N. and Albus, J.S.

"A Robotic Crane System Utilizing the Stewart Platform Configuration," Proceedings of the ISRAM '92 Conference, Santa Fe, NM, November 10-12, 1992

Albus, J.S.

"A Theory of Intelligent Systems," Chapter in Manufacturing & Automation Systems: Techniques & Technologies, Control & Dynamic Systems, Advances in Theory and Applications, Vol. 45, 1992

Schneiderman, H. and Albus, J.S.

"Progress and Prospects for Vision-Based Automatic Driving," Proceedings of the IVHS America '93 Conference, Washington, DC, April 14-17, 1993

Dagalakis, N.G., Albus, J.S., Bostelman, R.V. and Fiala, J.

"Development of the NIST Robot Crane Teleoperation Controller," Proceedings of the ANS Fifth Topical Meeting on Robotics and Remote Systems, Knoxville, TN, April 25-30, 1993

Albus, J., Meystel, A. and Uzzaman, S.

"Nested Motion Planning for an Autonomous Robot," Proceedings of the IEEE Regional Conference on Aerospace Control Systems, Westlake Village, CA, May 25-27, 1993

Albus, J.S.

"A Reference Model Architecture for Integrated Control," Proceedings of the US/ROC Joint Workshop on Automation and Productivity for Small to Medium Scale Manufacturing, Taipei, Taiwan, July 4-10, 1993

Albus, J.S.

"Task Decomposition," Proceedings of the 8th IEEE International Symposium on Intelligent Control, Chicago, IL, August 25-27, 1993

Bostelman, R.V. and Albus, J.S.

"Stability of an Underwater Work Platform Suspended from an Unstable Reference," Proceedings of the Oceans '93 Conference, Victoria, British Columbia, Canada, October 20, 1993

Albus, J.S.

"From Cerebellar Model Articulation Controller to a Reference Model for Intelligent Control," Proceedings of the 15th Annual International Conference IEEE Engineering in Medicine & Biology Society, San Diego, CA, October 28-31, 1993

Bostelman, R., Albus, J., Murphy, K., Tsai, T. and Amatucci, E.

"A Stewart Platform Lunar Rover," Proceedings of the Space '94 Conference, Albuquerque, NM, February 28 - March 3, 1994

AMATUCCI, Edward

Bostelman, R., Albus, J., Murphy, K., Tsai, T. and Amatucci, E.

"A Stewart Platform Lunar Rover," Proceedings of the Space '94 Conference, Albuquerque, NM, February 28 - March 3, 1994

BARBERA, Anthony J.

Evans, J.M., Albus, J.S. and Barbera, A.J.

"NBS/RIA Robotics Research Workshop," NBS Special Publication 500-29, Gaithersburg, MD, April 1978

Barbera, A.J., Albus, J.S. and Fitzgerald, M.L.

"Hierarchical Control of Robots using Microcomputers," Proceedings of the 9th International Symposium on Industrial Robots, Washington, DC, March 13-15, 1979

Albus, J.S., **Barbera**, A., Fitzgerald, M.L., Nagel, R., VanderBrug, G. and Wheatley, T.E. "A Measurement and Control Model for Adaptive Robots," Proceedings of the 10th International Symposium on Industrial Robots, Milan, Italy, March 1980

Albus, J.S., Barbera, A.J., Fitzgerald, M.L. and Nashman, M.

"Sensory Interactive," Robots 31st General Assembly of the International Institution for Production Engineering Research, Toronto, Canada, September 1, 1981

Albus, J.S., Barbera, A.J. and Nagel, R.N.

"Theory and Practice of Hierarchical Control," Proceedings of the 23rd IEEE Computer Society International Conference, Washington, DC, September 15-17, 1981

Smith, B.M., Albus, J.S. and Barbera, A.J.

"A Glossary of Terms for Robotics," NBSIR 81-2340, Gaithersburg, MD, October 1981

Barbera, A.J., Fitzgerald, M.L. and Albus, J.S.

"Concepts for a Real-Time Sensory-Interactive Control System Architecture," Proceedings of the Fourteenth Southeastern Symposium on System Theory, Blacksburg, VA, April 15-16, 1982

Albus, J.S., Mclean, C.R., Barbera, A.J. and Fitzgerald, M.L.

"Architecture for Real-Time Sensory-Interactive Control of Robots in a Manufacturing Facility," Proceedings of the Fourth IFAC/IFIP Symposium -- Information Control Problems in Manufacturing Technology, Gaithersburg, MD, October 26-28, 1982

Albus, J.S., Mclean, C.R., Barbera, A.J. and Fitzgerald, M.L.

"Hierarchical Control for Robots in an Automated Factory," Proceedings of the 13th International Symposium on Industrial Robots/Robots 7, Chicago, IL, April 18-21, 1983

Barbera, A.J., Fitzgerald, M.L., Albus, J.S. and Haynes, L.S.

"Language Independent Superstructure for Implementing Real-Time Control Systems," Proceedings of the International Workshop on High-Level Computer Architecture, Los Angeles, CA, May 21-25, 1984

Barbera, A.J., Fitzgerald, M.L., Albus, J.S. and Haynes, L.S.

"RCS: The NBS Real-Time Control System," Proceedings of the Robots 8 Conference and Exposition, Volume 2 - Future Considerations, Detroit, MI, June 4-7, 1984

Albus, J.S., **Barbera**, A.J., Fitzgerald, M.L., Kent, E.W., Scott, H.A. and Kilmer, R.D. "A Control System for an Automated Manufacturing Research Facility," Proceedings of the Robots 8 Conference and Exposition, Volume 2 - Future Considerations, Detroit, MI, June 4-7, 1984

Haynes, L.S., Barbera, A.J., Albus, J.S., Fitzgerald, M.L. and McCain, H.G.

"Application Example of the NBS Robot Control System," Robotics and Computer Integrated Manufacturing, Vol. 1, No. 1, pgs 81-95, 1984

Fitzgerald, M.L. and Barbera, A.J.

"Low-Level Control Interface for Robot Manipulators," Proceedings of the Workshop on Robot Standards (Sponsored by the National Bureau of Standards and the Navy Manufacturing Techn Pgm), Detroit, MI, June 6-7, 1985

Fitzgerald, M.L., Barbera, A.J. and Albus, J.S.

"Real-Time Control Systems for Robots," 1985 SPI National Plastics Exposition Conference, McCormick Place, Chicago, IL, June 17-21, 1985

Albus, J.S., Mclean, C.R., Barbera, A.J. and Fitzgerald, M.L.

"Hierarchical Control for Robots and Teleoperators," Proceedings of the IEEE Workshop on Intelligent Control 1985, Rensselaer Polytechnic Institute, Albany, NY, August 1985

Quintero, R. and Barbera, A.J.

"A Real-Time Control System Methodology for Developing Intelligent Control Systems," NISTIR 4936, Gaithersburg, MD, October 1992

Huang, H.M., Hira, R., Quintero, R. and Barbera, A.

"Applying the NIST Real-Time Control System Reference Model to Submarine Automation: A Maneuvering System Demonstration," NISTIR 5126, Gaithersburg, MD, February 1993

Horst, J.A. and Barbera, A.J.

"An Intelligent Control System for a Cutting Operation of a Continuous Mining Machine," NISTIR 5142, Gaithersburg, MD, March 1993

Quintero, R. and Barbera, A.J.

"A Task Oriented Approach for Developing Complex Large-Scale Intelligent Control Systems Using Software Templates," Proceedings of the 8th IEEE International Symposium on Intelligent Control, Chicago, IL, August 24-27, 1993

Quintero, R. and Barbera, A.J.

"A Software Template Approach to Building Complex Large-Scale Intelligent Control Systems," Proceedings of the 8th IEEE International Symposium on Intelligent Control, Chicago, IL, September 25-27, 1993

BARKMEYER, Edward

VanderBrug, G.J., Albus, J.S. and Barkmeyer, E.

"A Vision System for Real-Time Control of Robots," Proceedings of the 9th International Symposium on Industrial Robots, Washington, DC, March 13-15, 1979

Mclean, C., Mitchell, M. and Barkmeyer, E.

"Computer Architecture for Small-Batch Manufacturing," IEEE Spectrum, May 1983

Albus, J.S., Barkmeyer, E. and Jones, A.

"Approach to a System Architecture for Post Office Automation," Proceedings of the USPS 4th Advanced Technology Conference, Automation Technology Workshop, Washington, DC, November 5-7, 1990

BEUSAN, Sheri

Roche, M. and Beusan, S.

"Using Available Curve-Shaped Information with a Non-Uniform B-Spline," Computers in Mechanical Engineering, Vol. 5, No. 7, pgs 63-69, July 1987

BLIDBERG, D.R.

Albus, J.S. and Blidberg, D.R.

"Control System Architecture for Multiple Autonomous Undersea Vehicles (MAUV)," Proceedings of the Fifth International Symposium on Unmanned, Untethered Submersible Technology, Merrimack, NH, June 22-24, 1987

BLOODGOOD, John F.

Bloodgood, J.F.

"Survey on Robot Standards," Proceedings of the Workshop on Robot Standards, Detroit, MI, June 6-7, 1985

BLOOM, Howard M.

Furlani, C.M., Kent, E.W., Bloom, H.M. and Mclean, C.R.

"Automated Manufacturing Research Facility of the National Bureau of Standards," Summer Computer Simulation Conference, Vancouver, British Columbia, Canada, July 11-13, 1983

BOSTELMAN, Roger V.

Dagalakis, N.G., Albus, J.S., Goodwin, K.R., Lee, J.D., Tsai, T.M., Abrishamian, A., Bostelman, R. and Yancey, C.

"Robot Crane Technology (Final Report)," NISTTN 1267, Gaithersburg, MD, July 1989

Bostelman, R.

"Electronics Design of the Infrared/Ultrasonic Sensing for a Robot Gripper," NISTIR 89-4223, Gaithersburg, MD, November 1989

Bostelman, R.V.

"Description of a Vibration Compensation System for the Small Scale Model Robot Crane Project," NISTIR 4595, Gaithersburg, MD, July 1991

Szabo, S., Murphy, K.N., Scott, H.A., Legowik, S.A. and Bostelman, R.V.

"Control System Architecture for Unmanned Land Vehicles," Proceedings of the Association for Unmanned Vehicle Systems, Huntsville, AL, June 21-24, 1992

Albus, J.S., Bostelman, R.V. and Dagalakis, N.

"The NIST ROBOCRANE," Journal of Robotics System, Vol. 10, No. 5, pgs 709-724, Received March 3, 1992, accepted September 8, 1992

Bostelman, R.V., Dagalakis, N. and Albus, J.S.

"A Robotic Crane System Utilizing the Stewart Platform Configuration," Proceedings of the ISRAM '92 Conference, Santa Fe, NM, November 10-12, 1992

Szabo, S., Scott, H.A., Murphy, K.N., Legowik, S.A. and **Bostelman**, **R.V.** "High-Level Mobility Controller for a Remotely Operated Unmanned Land Vehicle," Journal of Intelligent and Robotic System, Vol. 5, pgs 63-77, 1992

Dagalakis, N.G., Albus, J.S., Bostelman, R.V. and Fiala, J.

"Development of the NIST Robot Crane Teleoperation Controller," Proceedings of the ANS Fifth Topical Meeting on Robotics and Remote Systems, Knoxville, TN, April 25-30, 1993

Bostelman, R.V. and Albus, J.S.

"Stability of an Underwater Work Platform Suspended from an Unstable Reference," Proceedings of the Oceans '93 Conference, Victoria, British Columbia, Canada, October 20, 1993

Bostelman, R., Albus, J., Murphy, K., Tsai, T. and Amatucci, E.

"A Stewart Platform Lunar Rover," Proceedings of the Space '94 Conference, Albuquerque, NM, February 28 - March 3, 1994

BROWN, Christopher

Coomb, D. and Brown, C.

"Localized Binocular Attention and Real-time Smooth Pursuit in Moving Robots," Working Notes of the AAAI Spring Symposium on Control of Selective Perception, Standford, CA, March 25-27 1992

Coombs, D. and Brown, C.

"Real-time Smooth Pursuit Tracking for a Moving Binocular Robot," NISTIR 4826, Gaithersburg, MD, April 1992

Coombs, D. and Brown, C.

"Real-time Smooth Pursuit Tracking for a Moving Binocular Robot," Proceeding of the Conference on Computer Vision and Pattern Recognition, Champaign, IL, June 15-18, 1992

Coombs, D. and Brown, C.

"Real-Time Binocular Smooth Pursuit," International Journal of Computer Vision 11:2, pp. 147-164, May 21, 1993

BUNCH, Wavne R.

Norcross, R.J., Bunch, W.R. and Kilmer, R.D.

"AMRF Composite Fabrication Workstation," Proceedings of the IEEE Third International Symposium on Robotics & Manufacturing (ISRAM), Burnaby, British Columbia, Canada, July, 18-20, 1990

CHACONAS, Karen

Nashman, M. and Chaconas, K.J.

"NBS Vision System in the AMRF," NBSIR 87-3684, Gaithersburg, MD, December 1987

Hong, T.H., Nashman, M. and Chaconas, K.

"Image Compression Technology and Techniques," Internal Report, April 1988

Nashman, M. and Chaconas, K.J.

"Low Level Image Processing Techniques Using the Pipeline Image Processing Engine in the Flight Telerobotic Servicer," Proceedings of the 1988 Goddard Conference on Space Applications of Artificial Intelligence, Goddard Space Flight Center, Greenbelt, MD, May 1988

Nashman, M. and Chaconas, K.J.

"NBS Vision System in the AMRF," Journal of Research of the National Bureau of Standards, Vol. 93, No. 4, July 1988

Herman, M., Chaconas, K., Nashman, M. and Hong, T.H.

"Low Data Rate Remote Vehicle Driving," Proceedings of the 3rd IEEE International Symposium on Intelligent Control, Arlington, VA, August 24-26, 1988

Herman, M., Chaconas, K., Nashman, M. and Hong, T.H.,

"Video Compression for Remote Vehicle Driving," Proceedings of the SPIE Advances in Intelligent Robotics Systems: Mobile Robots III, Vol. 1007, Cambridge, MA, November 1988

Chaconas, K.C. and Nashman, M.

"Visual Perception Processing in a Hierarchical Control System: Level 1," NISTTN 1260, Gaithersburg, MD, June 1989

Chaconas, K., Kelmar, L. and Nashman, M.

"NASREM Implementation of Position Determination from Motion," NISTIR 90-4293, Gaithersburg, MD, April 1990

Nashman, M. and Chaconas, K.

"Visual Perception Processing for the Flight Telerobotic Servicer Control System Level 1," Proceeding of the 1990 IEEE International Conference on Robotics and Automation, Cincinnati, OH, May 13-18, 1990

Chaconas, K.

"Range from Triangulation using an Inverse Perspective Method to Determine Relative Camera Pose," NISTIR 4385, Gaithersburg, MD, August 1990

Nashman, M. and Chaconas, K.

"Three-Dimensional Position Determination from Motion," Proceedings of the SPIE Conference on Advances in Intelligent Systems, Boston, MA, November 1990

Chaconas, K. and Nashman, M.

"Real-Time Model-Based Tracking Combining Spatial and Temporal Features," NISTIR 4610, Gaithersburg, MD, June 1991

Chaconas, K.C. and Nashman, M.

"Model-Based Feature Tracking," Journal of Intelligent and Robotic Systems, 1991

CHELLAPPA, Rama

Liu, H., Hong, T.H., Herman, M. and Chellappa, R.

"A Reliable Optical Flow Algorithm Using 3-D Hermite Polynomials," University of Maryland, Center for Automation Research Technical Report, College Park, MD, November 1993

Liu, H., Hong, T., Herman, M. and **Chellappa**, **R.**"A Reliable Optical Flow Algorithm Using 3-D Hermite Polynomials," NISTIR 5333, Gaithersburg, MD, December 1993

CLARK, Stephen N.

Manheimer, K.L., Clark, S.N., Warsaw, B.A. and Rowe, W.P.

"The Depot: A Framework for Sharing Software Installation Across Organizational and UNIX Platform Boundaries," NISTIR 4436, Gaithersburg, MD, September 1990

COOMBS, David

Coombs, D. and Brown, C.

"Localized Binocular Attention and Real-time Smooth Pursuit in Moving Robots," Working Notes of the AAAI Spring Symposium on Control of Selective Perception, Standford, CA, March 25-27 1992

Coombs, D. and Brown, C.

"Real-time Smooth Pursuit Tracking for a Moving Binocular Robot," NISTIR 4826, Gaithersburg, MD, April 1992

Coombs, D. and Brown, C.

"Real-time Smooth Pursuit Tracking for a Moving Binocular Robot," Proceeding of the Conference on Computer Vision and Pattern Recognition, Champaign, IL, June 15-18, 1992

Coombs, D. and Brown, C.

"Real-Time Binocular Smooth Pursuit," International Journal of Computer Vision 11:2, pp. 147-164, May 21, 1993

Herman, M., Szabo, S., Murphy, K., Coombs, D., Hong, T.H., Scott, H. and Dagalakis, N. "Recommendations for Performance Evaluation of Unmanned Ground Vehicle Technologies," NISTIR 5244, Gaithersburg, MD, August 1993

Coombs, D.

"RoboVac and the Cat Will Get Along Famously," Working Notes of the AAAI Fall Symposium on Instantiating Real-World Agents, Raleigh, NC, October 1993

Coombs, D.

"Sensor Fusion in Motion Perception," To be published in Behavioral and Brain Sciences target article "Motion Perception During Self-Motion"

CORBETT, G.K.

Corbett, G.K., Killough, S.M., Richardson, B.S. and Herman, M.

"Human Factors Testbed for Ground-Vehicle Telerobotics Research," Proceedings of the IEEE Southeast Conference '90, New Orleans, LA, April 1-4, 1990

DAGALAKIS, Nicholas G.

Albus, J.S., **Dagalakis**, N.G., Wang, B.L., Unger, J., Lee, J.D. and Yancey, C.W. "Available Robotics Technology for Applications in Heavy Industry," 1988 Iron and Steel Exposition and Annual Convention, Houston, TX, February 7-12, 1988

Dagalakis, N.G., Albus, J.S., Wang, B.L., Unger, J. and Lee, J.D.

"Stiffness Study of a Parallel Link Robot Crane for Shipbuilding Applications," Proceedings of the 7th International Conference for Offshore Mechanical and Arctic Engineering, Houston, TX, February 7-12, 1988

Lee, J.D., Albus, J.S., **Dagalakis**, N.G. and Tsai, T.M.

"Computer Simulation of a Parallel Link Manipulator," Robotics and Computer Integrated Manufacturing, August 1988

Unger, J., Dagalakis, N.G., Tsai, T.M. and Lee, J.D.

"Optimum Stiffness Study for a Parallel Link Robot Crane under Horizontal Force," Proceedings of the Second International Symposium on Robotics and Manufacturing Research, Education, and Applications, Albuquerque, NM, November 16-18, 1988

Dagalakis, N.G. and Lau, K.C.

"Optical Sensors for Robot Performance Testing and Calibration," Vision, Vol. 5, No. 3, pgs 10-14, Winter 1988

Lee, J.D., Albus, J.S., **Dagalakis**, N.G. and Tsai, T.M.

"Performance Measures of a Robotic Micropositioner," Proceedings of the 2nd International Symposium on Robotics and Manufacturing ASME, pgs 1047-1056, 1988

Dagalakis, N.G., Albus, J.S., Goodwin, K.R., Lee, J.D., Tsai, T.M., Abrishamian, A., Bostelman, R. and Yancey, C.

"Robot Crane Technology (Final Report)," NISTTN 1267, Gaithersburg, MD, July 1989

Dagalakis, N.G. and Wavering, A.J.

"Recommended Fine Positioning Test for the Development Test Flight (DTF-1) of the NASA Flight Telerobotic Servicer (FTS)," NISTIR 4478, Gaithersburg, MD, December 1990

Dagalakis, N.

"Robot Characterization Testing," NISTIR 4510, Gaithersburg, MD, January 1991

Albus, J.S., Quintero, R., Proctor, F., Michaloski, J., **Dagalakis**, N. and Tarnoff, N. "NIST Support to the Next Generation Controller Program: 1991 Final Technical Report," NISTIR 4888, Gaithersburg, MD, August 1992

Albus, J.S., Bostelman, R.V. and Dagalakis, N.

"The NIST ROBOCRANE," Journal of Robotics System, Vol. 10, No. 5, pgs 709-724, Received March 3, 1992, accepted September 8, 1992

Bostelman, R.V., **Dagalakis**, N. and Albus, J.S.

"A Robotic Crane System Utilizing the Stewart Platform Configuration," Proceedings of the ISRAM '92 Conference, Santa Fe, NM, November 10-12, 1992

Dagalakis, N.G., Albus, J.S., Bostelman, R.V. and Fiala, J.

"Development of the NIST Robot Crane Teleoperation Controller," Proceedings of the ANS Fifth Topical Meeting on Robotics and Remote Systems, Knoxville, TN, April 25-30, 1993

Herman, M., Szabo, S., Murphy, K., Coombs, D., Hong, T.H., Scott, H. and **Dagalakis**, N. "Recommendations for Performance Evaluation of Unmanned Ground Vehicle Technologies," NISTIR 5244, Gaithersburg, MD, August 1993

DAINIS, A.

Dainis, A. and Juberts, M.

"Accurate Remote Measurement of Robot Trajectory Motion," Proceedings of the IEEE International Conference on Robotics and Automation, St. Louis, MI, March 1985

DAMAZO, Brad

Proctor, F.M., Damazo, B., Yang, C. and Frechette, S.

"Open Architectures for Machine Control," NISTIR 5307, Gaithersburg, MD, December 1993

EVANS, John M.

Evans, J.M. and Albus, J.S.

"Guidelines for the Design and Procurement of a Low Cost Mobile Robot," NBSIR 76-995, Gaithersburg, MD, December 1975

Evans, J.M., Albus, J.S. and Barbera, A.J.

"NBS/RIA Robotics Research Workshop," NBS Special Publication 500-29, Gaithersburg, MD, April 1978

Evans, J.M.

"Measurement Technology for Automation in Construction and Large Scale Assembly," NBSIR 85-3210 Proceedings of a Workshop Sponsored by NBS and Transitions Research Corporation, February 5-6, 1985

FALCO, Joseph A.

Falco, J.A.

"AMRF Composites Fabrication Workstation: A Test Methodology to Measure the Quality of Thermoplastic Composite Parts," NISTIR 4552, Gaithersburg, MD, April 1991

FELDMAN, Philip

Huang, H.M., Hira, R. and Feldman, P.

"A Submarine Simulator Driven by a Hierarchical Real-Time Control System Architecture," NISTIR 4875, Gaithersburg, MD, July 1992

Huang, H.M., Hira, R. and Feldman, P.

"A Submarine Maneuvering System Demonstration Using a Generic Real-Time Control System (RCS) Reference Model," Proceedings of the Summer Computer Simulation Conference '92, Reno, NV, July 27-29, 1992

FIALA, John C.

Fiala, J.C. and Wavering, A.J.

"RCS Application Example: Tool Changing on a Horizontal Machining Center," Proceedings of the Second International Conference on Robotics and Factories of the Future, San Diego, CA, July 28-31, 1987

Fiala, J.C., Lumia, R. and Albus, J.S.

"Servo Level Algorithms for the NASREM Telerobot Control System Architecture," SPIE Volume 851, Proceedings of SPIE 1987 Cambridge Symposium of Advances Intelligent Robotic Systems, Cambridge, MA, November 2-4, 1987

Wavering, A.J. and Fiala, J.C.

"Real-Time Control System of the Horizontal Workstation Robot," NBSIR 88-3692, Gaithersburg, MD, December 1987

Lumia, R., Fiala, J.C. and Wavering, A.J.

"Architecture to Support Autonomy, Teleoperation, and Shared Control," Proceedings of the IEEE Conference on Systems, Man, and Cybernetics, Beijing, China, August 5-10, 1988

Fiala, J.C.

"Interfaces to Teleoperation Devices," NISTTN 1254, Gaithersburg, MD, October 1988

Fiala, J.C.

"Manipulator Servo Level Task Decomposition," NISTTN 1255, Gaithersburg, MD, October 1988

Lumia, R., Fiala, J. and Wavering, A.

"NASREM: Robot Control System and Testbed," Proceedings of the Second International Symposium on Robotics and Manufacturing Research, Education, and Applications, Alburquerque, NM, November 16-18, 1988

Lumia, R. and Fiala, J.

"Flight Telerobotic Servicer: From Functional Architecture to Computer Architecture," Proceedings of the 1989 Conference on Space Telerobotics, Pasadena, CA, January 31 - February 2, 1989

Albus, J.S., Lumia, R., Fiala, J. and Wavering, A.

"NASREM -- The NASA/NBS Standard Reference Model for Telerobot Control System Architecture," Proceedings of the 20th International Symposium on Industrial Robots, Tokyo, Japan, October 4-6, 1989

Lumia, R., Fiala, J.C. and Wavering, A.J.

"NASREM Robot Control System Standard," Robotics & Computer-Integrated Manufacturing, Vol. 6, No. 4, pgs 303-308, November 1989

Fiala, J.C.

"Note on NASREM Implementation," NISTIR 89-4215, Gaithersburg, MD, December 1989 (Issued March 1990)

Fiala, J.C. and Wavering, A.J.

"Implementation of a Jacobian-Transpose Algorithm," NISTIR 90-4286, Gaithersburg, MD, April 1990

Fiala, J.C. and Lumia, R.

"Approach to Telerobot Computing Architecture," NISTIR 4357, Gaithersburg, MD, June 1990

Fiala, J.

"Generation of Smooth Trajectories Without Planning," NISTIR 4622, Gaithersburg, MD, June 1991

Fiala, J.C. and Lumia, R.

"Adaptive Inertia Compensation Using a Cerebellar Model Algorithm," Proceedings of the International Joint Conference on Neural Networks, Singapore, November 18-21, 1991

Fiala, J., Wavering, A. and Lumia, R.

"A Manipulator Control Testbed: Implementation and Applications," Proceedings of the 15th Annual AAS Guidance and Control Conference, Keystone, CO, February 8-12, 1992

Fiala, J. and Lumia, R.

"The Effect of Time-Delay and Discrete Control on the Contact Stability of Simple Position Controllers," Proceedings of the 1992 IEEE International Conference on Robotics and Automation, Nice, France, May 10-15, 1992

Fiala, J. and Wavering, A.

"Experimental Evaluation of Cartesian Stiffness Control on a Seven Degree-of-Freedom Robot Arm," Journal of Intelligent and Robotic Systems, Vol. 5, pgs 5-24, 1992

Dagalakis, N.G., Albus, J.S., Bostelman, R.V. and Fiala, J.

"Development of the NIST Robot Crane Teleoperation Controller," Proceedings of the ANS Fifth Topical Meeting on Robotics and Remote Systems, Knoxville, TN, April 25-30, 1993

Wavering, A.J., Fiala, J.C., Roberts, K.J. and Lumia, R.

"TRICLOPS: A High-Performance Trinocular Active Vision System," Proceedings of the IEEE Conference on Robotics and Automation, Atlanta, GA, May 2-6, 1993

Fiala, J.C., Lumia, R., Roberts, K.J. and Wavering, A.J.

"TRICLOPS: A Tool for Studying Active Vision," Submitted to International Journal of Computer Vision

FITZGERALD, M.L.

Barbera, A.J., Albus, J.S. and Fitzgerald, M.L.

"Hierarchical Control of Robots using Microcomputers," Proceedings of the 9th International Symposium on Industrial Robots, Washington, DC, March 13-15, 1979

Albus, J.S., Barbera, A., **Fitzgerald, M.L.**, Nagel, R., VanderBrug, G. and Wheatley, T.E. "A Measurement and Control Model for Adaptive Robots," Proceedings of the 10th International Symposium on Industrial Robots, Milan, Italy, March 1980

Albus, J.S., Barbera, A.J., Fitzgerald, M.L. and Nashman, M.

"Sensory Interactive," Robots 31st General Assembly of the International Institution for Production Engineering Research, Toronto, Canada, September 1, 1981

Barbera, A.J., Fitzgerald, M.L. and Albus, J.S.

"Concepts for a Real-Time Sensory-Interactive Control System Architecture," Proceedings of the Fourteenth Southeastern Symposium on System Theory, Blacksburg, VA, April 15-16, 1982

Albus, J.S., Mclean, C.R., Barbera, A.J. and Fitzgerald, M.L.

"Architecture for Real-Time Sensory-Interactive Control of Robots in a Manufacturing Facility," Proceedings of the Fourth IFAC/IFIP Symposium -- Information Control Problems in Manufacturing Technology, Gaithersburg, MD, October 26-28, 1982

Albus, J.S., Mclean, C.R., Barbera, A.J. and Fitzgerald, M.L.

"Hierarchical Control for Robots in an Automated Factory," Proceedings of the 13th International Symposium on Industrial Robots/Robots 7, Chicago, IL, April 18-21, 1983

Barbera, A.J., Fitzgerald, M.L., Albus, J.S. and Haynes, L.S.

"Language Independent Superstructure for Implementing Real-Time Control Systems," Proceedings of the International Workshop on High-Level Computer Architecture, Los Angeles, CA, May 21-25, 1984

Barbera, A.J., Fitzgerald, M.L., Albus, J.S. and Haynes, L.S.

"RCS: The NBS Real-Time Control System," Proceedings of the Robots 8 Conference and Exposition, Volume 2 - Future Considerations, Detroit, MI, June 4-7, 1984

Albus, J.S., Barbera, A.J., **Fitzgerald, M.L.**, Kent, E.W., Scott, H.A. and Kilmer, R.D. "A Control System for an Automated Manufacturing Research Facility," Proceedings of the Robots 8 Conference and Exposition, Volume 2 - Future Considerations, Detroit, MI, June 4-7, 1984

Haynes, L.S., Barbera, A.J., Albus, J.S., Fitzgerald, M.L. and McCain, H.G.

"Application Example of the NBS Robot Control System," Robotics and Computer Integrated Manufacturing, Vol. 1, No. 1, pgs 81-95, 1984

Fitzgerald, M.L. and Barbera, A.J.

"Low-Level Control Interface for Robot Manipulators," Proceedings of the Workshop on Robot Standards (Sponsored by the National Bureau of Standards and the Navy Manufacturing Techn Pgm), Detroit, MI, June 6-7, 1985

Fitzgerald, M.L., Barbera, A.J. and Albus, J.S.

"Real-Time Control Systems for Robots," 1985 SPI National Plastics Exposition Conference, McCormick Place, Chicago, IL, June 17-21, 1985

Albus, J.S., Mclean, C.R., Barbera, A.J. and Fitzgerald, M.L.

"Hierarchical Control for Robots and Teleoperators," Proceedings of the IEEE Workshop on Intelligent Control 1985, Rensselaer Polytechnic Institute, Albany, NY, August 1985

FORTMANN, T.E.

Johnson, T.L., Milligan, S.D. and Fortmann, T.E.

"Hierarchical Control System Emulation Applications Guide," NBS-GCR-82-410, January 1985

FRECHETTE, Simon

Proctor, F.M., Damazo, B., Yang, C. and Frechette, S.

"Open Architectures for Machine Control," NISTIR 5307, Gaithersburg, MD, December 1993

FURLANI, Cita M.

Furlani, C.M., Kent, E.W., Bloom, H.M. and Mclean, C.R.

"Automated Manufacturing Research Facility of the National Bureau of Standards," Summer Computer Simulation Conference, Vancouver, British Columbia, Canada, July 11-13, 1983

Furlani, C.M.

"Hierarchical Control System Emulation Programmer's Manual," NBSIR-85-3157, Gaithersburg, MD, January 1985

GOODWIN, Kenneth

Dagalakis, N.G., Albus, J.S., Goodwin, K.R., Lee, J.D., Tsai, T.M., Abrishamian, A., Bostelman, R. and Yancey, C.

"Robot Crane Technology (Final Report)," NISTTN 1267, Gaithersburg, MD, July 1989

Albus, J.S., Quintero, R., Lumia, R., Herman, M., Kilmer, R. and **Goodwin, K.** "Concept for a Reference Model Architecture for Real-Time Intelligent Control Systems (ARTICS)," NISTTN 1277, Gaithersburg, MD, April 1990

Albus, J.S., Quintero, R., Lumia, R., Herman, M., Kilmer, R. and **Goodwin, K.** "A Reference Model Architecture for ARTICS," ASME Manufacturing Review, Vol. 4, No. 3, September 1991

Hira, R., Quintero, R., **Goodwin, K.** and Siewert, T. "Report on Mobility for Welding Automation in Ship Construction," NISTIR 5301, Gaithersburg, MD, December 1993

HAAR, R.

Shneier, M., Nagalia, S., Albus, J.S. and Haar, R.

"Visual Feedback for Robot Control," Proceedings of the International Workshop on Industrial Applications of Machine Vision, Research Triangle, NC, May 3-5, 1982

HAYNES, Lenard S.

Barbera, A.J., Fitzgerald, M.L., Albus, J.S. and Haynes, L.S.

"Language Independent Superstructure for Implementing Real-Time Control Systems," Proceedings of the International Workshop on High-Level Computer Architecture, Los Angeles, CA, May 21-25, 1984

Barbera, A.J., Fitzgerald, M.L., Albus, J.S. and Haynes, L.S.

"RCS: The NBS Real-Time Control System," Proceedings of the Robots 8 Conference and Exposition, Volume 2 - Future Considerations, Detroit, MI, June 4-7, 1984

Haynes, L.S., Barbera, A.J., Albus, J.S., Fitzgerald, M.L. and McCain, H.G.

"Application Example of the NBS Robot Control System," Robotics and Computer Integrated Manufacturing, Vol. 1, No. 1, pgs 81-95, 1984

Lau, K., Hocken, R. and Haynes, L.

"Robot Performance Measurements Using Automatic Laser Techniques," NBS-Navy NAV/CIM Workshop on Robot Standards, Detroit, MI, June 6-7, 1985

Lee, J.D. and Haynes, L.S.

"Finite-Element Analysis of Flexible Fixturing System," Journal of Engineering for Industry, May 1987

Lee, J.D., Haynes, L.S., Wang, B.L. and Tsai, T.M.

"Control of Flexible Robot Arm," Modelings and Control of Robotic Manipulators and Manufacturing Processes, SME, pgs 241-251, 1987

HENRICI, G.S.

Kent, E.W., Shneier, M.O., Lumia, R., Herriman, M., Luck, R.L. and **Henrici**, **G.S.** "Architecture of the NBS Pipelined Image Processing Engine," Conference on Algorithm-Guide Parallel Architectures for Automatic Target Recognition, Leesburg, VA, 1984

HERMAN, Martin

Herman, M., Kanade, T. and Kuroe, S.

"Incremental Acquisition of a Three-Dimensional Scene Model from Images," Proceedings of the IEEE Transactions on Pattern Analysis and Machine Intelligence, Vol. PAMI-6, No. 3, May 1984

Herman, M.

"Fast, Three-Dimensional, Collision-Free Motion Planning," Proceedings of the IEEE International Conference on Robotics and Automation, pgs 1056-1063, San Francisco, CA, April 1986

Herman, M.

"Fast Path Planning in Unstructured, Dynamic, 3-D Worlds," Proceedings of SPIE Conference on Applications of Artificial Intelligence III, pgs 505-512, Orlando, FL, April 1986

Herman, M.

"Merging 3-D Symbolic Descriptions Obtained from Multiple Views of a Scene," Proceedings of the SPIE Advances in Intelligent Robotics Systems, Inteligent Robots and Computer Vision, pgs 292-298, Cambridge, MA, October 1986

Herman, M. and Kanade, T.

"Incremental Reconstruction of 3D Scenes from Multiple Complex Images," Artifical Intelligence, Vol. 30, No. 3, pgs 289-341, December 1986

Herman, M.

"Representation and Incremental Construction of a Three-Dimensional Scene Model," Techniques for 3-D Machine Perception, A. Rosenfeld (Editor) Elsevier Science Publishers B.V. (North-Holland), 1986

Shneier, M.O., Lumia, R. and Herman, M.

"Prediction-Based Vision for Robot Control," Computer Magazine, pgs 46-55, February 1987

Walker, E.L., Herman, M. and Kanade, T.

"Framework for Representing and Reasoning about Three-Dimensional Objects for Vision," AI Magazine, Vol. 9, No. 2. pgs 47-58, October 1987

Herman, M. and Albus, J.S.

"Real-Time Hierarchical Planning for Multiple Mobile Robots," Proceedings of the DARPA Knowledge-Based Planning Workshop, Austin, TX, December 8-10, 1987

Herman, M.

"Application of the Pipe Image Processing Machine to Scanning Microscopy,". Proceedings of the SPIE Scanning Microscopy Technologies and Applications, Vol. 897, pgs 163-173, Los Angeles, CA, January 1988

Herman, M. and Albus, J.S.

"Overview of the Multiple Autonomous Underwater Vehicles (MAUV) Project," 1988 IEEE International Conference on Robotics and Automation, Philadelphia, PA, April 1988

Herman, M., Chaconas, K., Nashman, M. and Hong, T.H.

"Low Data Rate Remote Vehicle Driving," Proceedings of the 3rd IEEE International Symposium on Intelligent Control, Arlington, VA, August 24-26, 1988

Herman, M., Hong, T.H., Swetz, S., Oskard, D. and Rosol, M.

"Planning and World Modeling for Autonomous Undersea Vehicles," Proceedings of the Third IEEE International Symposium on Intelligent Control, Arlington, VA, August 24-26, 1988

Herman, M., Chaconas, K., Nashman, M. and Hong, T.H.

"Video Compression for Remote Vehicle Driving," Proceedings of the SPIE Advances in Intelligent Robotics Systems: Mobile Robots III, Vol. 1007, Cambridge, MA, November 1988

Walker, E.L. and Herman, M.

"Geometric Reasoning for Constructing 3D Scene Descriptions from Images" Artificial Intelligence, Vol. 37, No. 1-3, pgs 275-290, December 1988

Albus, J.S., Quintero, R., Lumia, R., Herman, M., Kilmer, R. and Goodwin, K.

"Concept for a Reference Model Architecture for Real-Time Intelligent Control Systems (ARTICS)," NISTTN 1277, Gaithersburg, MD, April 1990

Rangachar, R., Hong, T., Herman, M., Luck, R. and Lupo, J.

"Real-Time Differential Range Estimation Based on Time-Space Imagery Using Pipe," Proceedings of the SPIE Real-Time Image Processing II: Algorithms, Architectures, & Applications, Vol. 1295, Orlando, FL, April 1990

Rangachar, R., Hong, T., Herman, M. and Lupo, J.

"Real-Time Implementation of a Differential Range Finder," Proceedings of the SPIE Real-Time Image Processing II: Algorithms, Architectures. & Applications, Vol. 1295, Orlando, FL, April 1990

Corbett, G.K., Killough, S.M., Richardson, B.S. and Herman, M.

"Human Factors Testbed for Ground-Vehicle Telerobotics Research," Proceedings of the IEEE Southeast Conference '90, New Orleans, LA, April 1-4, 1990

Raviv, D. and Herman, M.

"Towards an Understanding of Camera Fixation," Proceedings of the IEEE International Conference on Robotics and Automation, Cincinnati, OH, May 1990

Yakali, H.H., Raviv, D. and Herman, M.

"Integrated Mobile Robot System for Testing Vision Algorithms," Proceedings of the 3rd Conference on Recent Advances in Robotics, Florida Atlantic University, Boca Raton, FL, July 2-3, 1990

Herman, M., Albus, J. and Hong, T.H.

"Real-Time Vision for Unmanned Vehicles," Proceedings of the Sensors Exposition, pgs 206c-1 to 206c-12, Chicago, IL, September 1990

Herman, M., Albus, J.S. and Hong, T.H.

"Intelligent Control for Multiple Autonomous Undersea Vehicles," Neural Networks for Control, Miller, W.T. and Sutton, R., Eds., MIT Press: Cambridge, MA, Fall 1990

Rangachar, R., Hong, T.H., Herman, M. and Luck R.

"Analysis of Optical Flow Estimation Using Epipolar Plane Images," Proceedings of the SPIE Advances in Intelligent Systems: Intelligent Robots and Computer Vision, Boston, MA, November 1990

Herman, M. and Hong, T.H.

"Visual Navigation Using Optical Flow," NATO Defense Research Group Seminar on Robotics in the Battlefield, Paris, France, March 1991

Rangachar, R., Hong, T.H., Herman, M. and Luck, R.

"Analysis of Optical Flow Estimation Using Epipolar Plane Images," NISTIR 4569, Gaithersburg, MD, April 1991

Rangachar, R., Hong, T.H., Herman, M. and Luck, R.

"Three Dimensional Reconstruction From Optical Flow Using Temporal Integration," NISTIR 4570, Gaithersburg, MD, April 1991

Yakali, H.H., Raviv, D. and Herman, M.

"Road Following -- A New Approach," Proceedings of the Fourth Annual Conference on Recent Advances in Robotics, Boca Raton, FL, May 1991

Raviv, D. and Herman, M.

"Visual Control Signals for Road Following," Proceedings of the 1991 IEEE International Symposium on Intelligent Control, Arlington, VA, August 1991

Albus, J.S., Quintero, R., Lumia, R., Herman, M., Kilmer, R. and Goodwin, K.

"A Reference Model Architecture for ARTICS," ASME Manufacturing Review, Vol. 4, No. 3, September 1991

Raviv, D. and Herman, M.

"A New Approach to Vision-Based Road Following for Autonomous Vehicles," Proceedings the of IEEE International Conference on Systems, Man & Cybernetics, Charlottesville, VA and Proceedings of the IEEE Workshop on Visual Motion, Princeton, NJ, October 1991

Raviv, D. and Herman, M.

"A New Approach to Vision and Control for Road Following," NISTIR 4476, Gaithersburg, MD, January 1991 & Proceedings of the IEEE Workshop on Visual Motion, Princeton, NJ, October 7-9, 1991

Raviv, D. and Herman, M.

"A "Nonreconstruction" Approach for Road Following," Proceedings of the SPIE Conference on Intelligent Robots and Computer Vision X, Boston, MA, November 1991

Yakali, H.H., Raviv, D. and Herman, M.

"New Vision-Based Approach for Navigation," Proceedings of the SPIE Advances in Intelligent Robotics Systems: Mobile Robots VI, Vol. 1613, Boston, MA, November 1991

Young, G.S., Hong, T.H., Herman, M. and Yang, J.C.S.

"Kinematic Calibration of an Active Camera System," NISTIR 4715, Gaithersburg, MD, November 1991

Herman, M., Albus, J.S. and Hong, T.H.

"Real-Time Vision for Autonomous and Teleoperated Control of Unmanned Vehicles," Active Perception and Robot Vision, Sood, A., ed., Springer-Verlag: Heidelberg, 1991

Young, G.S., Hong, T.H., Herman, M. and Yang, J.C.S.

"Kinematic Calibration of an Active Camera System," Proceedings of the 1992 IEEE Computer Society Conference on Computer Vision and Pattern Recognition, Champaign, IL, June 15-18, 1992

Young, G.S., Hong, T.H. and Herman, M.

"Obstacle Detection for a Vehicle Using Optical Flow," Proceedings of the Intelligent Vehicles '92 Conference, Detroit, MI, June 29 - July 1, 1992

Lau, H., Hong, T.H. and Herman, M.

"Optimal Estimation of Optical Flow, Time-to-contact and Depth," NISTIR 4919, Gaithersburg, MD, September 1992

Raviv, D. and Herman, M.

"Visual Servoing for Robot Vehicles Using Relevant 2-D Image Cues," NISTIR 4921, Gaithersburg, MD, September 1992

Young, G.S., Hong, T.H., Herman, M. and Yang, J.C.S.

"Obstacle Detection and Terrain Characterization Using Optical Flow Without 3-D Reconstruction," Proceedings of the SPIE 1825 on Intelligent Robots and Computer Vision XI, Boston, MA, November 16-18, 1992

Young, G.S., Hong, T.H., Herman, M. and Yang, J.C.S.

"New Visual Invariants for Obstacle Detection Using Optical Flow Induced From General Motion," Proceedings of the IEEE Workshop on Applications of Computer Vision, Palm Spring, CA, November 30-December 2, 1992

Raviv, D. and Herman, M.

"Visual Servoing Using Relevant 2-D Image Cues," Proceedings of the Intelligent Vehicles '93 Conference, Tokyo, Japan, July 14-16, 1993

Herman, M.

"Report of the ARPA/NIST Workshop on Performance Evaluation of Unmanned Ground Vehicle Technologies," NISTIR 5237, Gaithersburg, MD, August 1993

Herman, M., Szabo, S., Murphy, K., Coombs, D., Hong, T.H., Scott, H. and Dagalakis, N. "Recommendations for Performance Evaluation of Unmanned Ground Vehicle Technologies," NISTIR 5244, Gaithersburg, MD, August 1993

Young, G.S., Hong, T.H., Herman, M. and Yang, J.C.S.

"Safe Navigation for Autonomous Vehicles: A Purposive and Direct Solution," Proceedings of the SPIE Conference on Intelligent Robots and Computer Vision XII: Active Vision and 3D Methods, Boston, MA, September 1993

Herman, M., Raviv, D., Schneiderman, H. and Nashman, M.

"Visual Road Following Without 3-D Reconstruction," Proceedings of the SPIE 22nd Applied Imagery Pattern Recognition Workshop, Vol. 2103, Washington, DC, October 1993

Liu, H., Hong, T.H., **Herman, M.** and Chellappa, R.

"A Reliable Optical Flow Algorithm Using 3-D Hermite Polynomials," University of Maryland, Center for Automation Research Technical Report, College Park, MD, November 1993

Liu, H., Hong, T., **Herman**, M. and Chellappa, R.

"A Reliable Optical Flow Algorithm Using 3-D Hermite Polynomials," NISTIR 5333, Gaithersburg, MD, December 1993

HERRIMAN, M.

Kent, E.W., Shneier, M.O., Lumia, R., **Herriman, M.**, Luck, R.L. and Henrici, G.S. "Architecture of the NBS Pipelined Image Processing Engine," Conference on Algorithm-Guide Parallel Architectures for Automatic Target Recognition, Leesburg, VA, 1984

HIRA, Ron

Huang, H.M., Hira, R. and Feldman, P.

"A Submarine Simulator Driven by a Hierarchical Real-Time Control System Architecture," NISTIR 4875, Gaithersburg, MD, July 1992

Huang, H.M., Hira, R. and Feldman, P.

"A Submarine Maneuvering System Demonstration Using a Generic Real-Time Control System (RCS) Reference Model," Proceedings of the Summer Computer Simulation Conference '92, Reno, NV, July 27-29, 1992

Huang, H.M., Hira, R., Quintero, R. and Barbera, A.

"Applying the NIST Real-Time Control System Reference Model to Submarine Automation: A Maneuvering System Demonstration," NISTIR 5126, Gaithersburg, MD, February 1993

Huang, H.M., Hira, R. and Quintero, R.

"A Submarine Maneuvering System Demonstration Based on the NIST Real-Time Control System Reference Model," Proceedings of the 8th IEEE International Symposium on Intelligent Control, Chicago, IL, August 24-27, 1993

Hira, R., Quintero, R., Goodwin, K. and Siewert, T.

"Report on Mobility for Welding Automation in Ship Construction," NISTIR 5301, Gaithersburg, MD, December 1993

HOCKEN, Robert J.

Simpson, J.A., Hocken, R.J. and Albus, J.S.

"Automated Manufacturing Research Facility of the National Bureau of Standards," Journal of Manufacturing Systems: Society of Manufacturing Engineers, 1(1): pgs 17-32, 1982

Lau, K., Hocken, R. and Haynes, L.

"Robot Performance Measurements Using Automatic Laser Techniques," NBS-Navy NAV/CIM Workshop on Robot Standards, Detroit, MI, June 6-7, 1985

HONG, Tsai-Hong

Shneier, M.O., Rutowski, W.S. and Hong, T.H.

"Using Chebyshev Polynomials for Interpreting Structured Light Images," Proceedings of the IEEE International Conference on Robotics and Automation, April 1985

Hong, T.H. and Shneier, M.O.

"Describing a Robot's Workspace using a Sequence of Views from a Moving Camera," IEEE Transactions on Pattern Analysis and Machine Intelligence, Vol. PAMI-7, No. 6, November 1985

Kent, E.W., Shneier, M.O. and Hong, T.H.

"Building Representations From Fusion of Multiple Views," Proceedings of the IEEE International Conference on Robotics and Automation, San Francisco, CA, April 7-10, 1986

Hong, T. H. and Shneier, M.O.

"Rotation and Translation of Objects Represented by Octrees," Proceedings of the International Conference on Pattern Recognition, Paris, France, 1986

Hong, T. H., Nashman, M. and Chaconas, K.

"Image Compression Technology and Techniques," Internal Report, April 1988

Herman, M., Chaconas, K., Nashman, M. and Hong, T.H.

"Low Data Rate Remote Vehicle Driving," Proceedings of the 3rd IEEE International Symposium on Intelligent Control, Arlington, VA, August 24-26, 1988

Herman, M., Hong, T.H., Swetz, S., Oskard, D. and Rosol, M.

"Planning and World Modeling for Autonomous Undersea Vehicles," Proceedings of the Third IEEE International Symposium on Intelligent Control, Arlington, VA, August 24-26, 1988

Herman, M., Chaconas, K., Nashman, M. and **Hong, T.H.** "Video Compression for Remote Vehicle Driving," Proceedings of the SPIE Advances in Intelligent Robotics Systems: Mobile Robots III, Vol. 1007, Cambridge, MA, November 1988

Oskard, D.N., Hong, T.H. and Shaffer, C.A.

"Real-Time Algorithms and Data Structures for Underwater Mapping," Proceedings of the SPIE Advances in Intelligent Robotics Systems Conference, Boston, MA, November 10-11, 1988

Rangachar, R., Hong, T., Herman, M., Luck, R. and Lupo, J.

"Real-Time Differential Range Estimation Based on Time-Space Imagery Using Pipe," Proceedings of the SPIE Real-Time Image Processing II: Algorithms, Architectures, & Applications, Vol. 1295, Orlando, FL, April 1990

Rangachar, R., Hong, T., Herman, M. and Lupo, J.

"Real-Time Implementation of a Differential Range Finder," Proceedings of the SPIE Real-Time Image Processing II: Algorithms, Architectures. & Applications, Vol. 1295, Orlando, FL, April 1990

Albus, J.S. and Hong, T.H.

"Motion, Depth, and Image Flow," Proceedings of the 1990 IEEE International Conference on Robotics & Automation, Cincinnati, OH, May 13-18, 1990

Herman, M., Albus, J. and Hong, T.H.

"Real-Time Vision for Unmanned Vehicles," Proceedings of the Sensors Exposition, pgs 206c-1 to 206c-12, Chicago, IL, September 1990

Herman, M., Albus, J.S. and Hong, T.H.

"Intelligent Control for Multiple Autonomous Undersea Vehicles," Neural Networks for Control, Miller, W. T. and Sutton, R., Eds., MIT Press: Cambridge, MA, Fall 1990

Rangachar, R., Hong, T. H., Herman, M. and Luck R.

"Analysis of Optical Flow Estimation Using Epipolar Plane Images," Proceedings of the SPIE Advances in Intelligent Systems: Intelligent Robots and Computer Vision, Boston, MA, November 1990

Herman, M. and Hong, T.H.

"Visual Navigation Using Optical Flow," NATO Defense Research Group Seminar on Robotics in the Battlefield, Paris, France, March 1991

Rangachar, R., Hong, T.H., Herman, M. and Luck, R.

"Analysis of Optical Flow Estimation Using Epipolar Plane Images," NISTIR 4569, Gaithersburg, MD, April 1991

Rangachar, R., Hong, T.H., Herman, M. and Luck, R.

"Three Dimensional Reconstruction From Optical Flow Using Temporal Integration," NISTIR 4570, Gaithersburg, MD, April 1991

Young, G.S., Hong, T.H., Herman, M. and Yang, J.C.S.

"Kinematic Calibration of an Active Camera System," NISTIR 4715, Gaithersburg, MD, November 1991

Herman, M., Albus, J.S. and Hong, T.H.

"Real-Time Vision for Autonomous and Teleoperated Control of Unmanned Vehicles," Active Perception and Robot Vision, Sood, A., ed., Springer-Verlag: Heidelberg, 1991

Young, G.S., Hong, T.H., Herman, M. and Yang, J.C.S.

"Kinematic Calibration of an Active Camera System," Proceedings of the 1992 IEEE Computer Society Conference on Computer Vision and Pattern Recognition, Champaign, IL, June 15-18, 1992

Young, G.S., Hong, T.H. and Herman, M.

"Obstacle Detection for a Vehicle Using Optical Flow," Proceedings of the Intelligent Vehicles '92 Conference, Detroit, MI, June 29 - July 1, 1992

Lau, H., Hong, T.H. and Herman, M.

"Optimal Estimation of Optical Flow, Time-to-contact and Depth," NISTIR 4919, Gaithersburg, MD, September 1992

Young, G.S., Hong, T.H., Herman, M. and Yang, J.C.S.

"Obstacle Detection and Terrain Characterization Using Optical Flow Without 3-D Reconstruction," Proceedings of the SPIE 1825 on Intelligent Robots and Computer Vision XI, Boston, MA, November 16-18, 1992

Young, G.S., Hong, T.H., Herman, M. and Yang, J.C.S.

"New Visual Invariants for Obstacle Detection Using Optical Flow Induced From General Motion," Proceedings of the IEEE Workshop on Applications of Computer Vision, Palm Spring, CA, November 30-December 2, 1992

Herman, M., Szabo, S., Murphy, K., Coombs, D., **Hong, T.H.**, Scott, H. and Dagalakis, N. "Recommendations for Performance Evaluation of Unmanned Ground Vehicle Technologies," NISTIR 5244, Gaithersburg, MD, August 1993

Young, G.S., Hong, T.H., Herman, M. and Yang, J.C.S.

"Safe Navigation for Autonomous Vehicles: A Purposive and Direct Solution," Proceedings of the SPIE Conference on Intelligent Robots and Computer Vision XII: Active Vision and 3D Methods, Boston, MA, September 1993

Liu, H., Hong, T. H., Herman, M. and Chellappa, R.

"A Reliable Optical Flow Algorithm Using 3-D Hermite Polynomials," University of Maryland, Center for Automation Research Technical Report, College Park, MD, November 1993

Liu, H., Hong, T., Herman, M. and Chellappa, R.

"A Reliable Optical Flow Algorithm Using 3-D Hermite Polynomials," NISTIR 5333, Gaithersburg, MD, December 1993

HORST, John A.

Horst, J.A.

"Application of Measurement Error Propagation Theory to Two Measurement Sys Used To Calculate the Position and Heading of a Vehicle on a Flat Surface," NISTIR 4434, Gaithersburg, MD, September 1990

Horst, J.A.

"Assembly Code to Compute Sine and Cosine Using the CORDIC Algorithm," NISTIR 4480, Gaithersburg, MD, December 1990

Huang, H.M., Horst, J. and Quintero, R.

"Task Decomposition and Algorithm Development for Real-Time Motion Control of a Continuous Mining Machine," NISTIR 4596, Gaithersburg, MD, May 1991

Horst, J.A.

"Computing Depth From Temporal Cross-Correlation: A Comparison of Two Methods of Computation," NISTIR 4764, Gaithersburg, MD, February 1992

Horst, J.A. and Barbera, A.J.

"An Intelligent Control System for a Cutting Operation of a Continuous Mining Machine," NISTIR 5142, Gaithersburg, MD, March 1993

Horst, J.A.

"Coal extraction using RCS," Proceedings of the 8th IEEE International Symposium on Intelligent Control, Chicago, IL, August 24-27, 1993

Horst, J.A.

"Servo Control of a Coal Mining Machine Appendage and Integration into a Real-Time Control System (RCS) Design," Proceedings of the 8th IEEE International Symposium on Intelligent Control, 1993

HUANG, Huang-Min

Albus, J.S., Quintero, R., Huang, H.M. and Roche, M.

"Mining Automation Real-Time Control System Architecture Standard Reference Model (MASREM)," NISTTN 1261, Volume 1, Gaithersburg, MD, May 1989

Huang, H.M.

"Hierarchical Real-Time Control Task Decomposition for a Coal Mining Automation Project," NISTIR 90-4271, Gaithersburg, MD, March 1990

Huang, H.M.

"Hierarchical Real-Time Control System for Use with Coal Mining Automation," Proceedings of the Fourth Conference on the Use of Computers in the Coal Industry, Morgantown, WVA, June 1990

Huang, **H.M**. and Quintero, R.

"Task Decomposition Methodology for the Design of a Coal Mining Automation Hierarchical Real-Time Control System," Proceedings of the 5th IEEE International Symposium on Intelligent Control, Philadelphia, PA, September 5-7, 1990

Huang, H.M., Horst, J. and Quintero, R.

"Task Decomposition and Algorithm Development for Real-Time Motion Control of a Continuous Mining Machine," NISTIR 4596, Gaithersburg, MD, May 1991

Huang, H.M., Quintero, R. and Albus, J.S.

"A Reference Model, Design Approach, and Development Illustration toward Hierarchical Real-Time System Control for Coal Mining Operations," Advances in Control & Dynamic Systems, Academic Press, July 1991 Huang, H.M., Hira, R. and Feldman, P.

"A Submarine Simulator Driven by a Hierarchical Real-Time Control System Architecture," NISTIR 4875, Gaithersburg, MD, July 1992

Huang, H.M., Hira, R. and Feldman, P.

"A Submarine Maneuvering System Demonstration Using a Generic Real-Time Control System (RCS) Reference Model," Proceedings of the Summer Computer Simulation Conference '92, Reno, NV, July 27-29, 1992

Huang, H.M., Hira, R., Quintero, R. and Barbera, A.

"Applying the NIST Real-Time Control System Reference Model to Submarine Automation: A Maneuvering System Demonstration," NISTIR 5126, Gaithersburg, MD, February 1993

Huang, H.M., Hira, R. and Quintero, R.

"A Submarine Maneuvering System Demonstration Based on the NIST Real-Time Control System Reference Model," Proceedings of the 8th IEEE International Symposium on Intelligent Control, Chicago, IL, August 24-27, 1993

JACOFF, Adam

Tarnoff, N., Jacoff, A. and Lumia, R.

"World Model Registration for Effective Off-Line Programming of Robots," Proceedings of the IEEE Third International Symposium on Robotics and Manufacturing (ISRAM 90), Burnaby, British Columbia, Canada, July 18-20, 1990

Tarnoff, N., Jacoff, A. and Lumia, R.

"Graphical Simulation for Sensor-Based Robot Programming," Journal of Intelligent and Robotic Systems, Vol. 5, pgs 49-62, 1992

JOARDER, Kunal

Joarder, K. and Raviv, D.

"Autonomous Obstacle Avoidance Using Visual Fixation and Looming," NISTIR 4996, Gaithersburg, MD, December 1992

JOHNSON, Tim L.

Johnson, T.L., Milligan, S.D. and Fortmann, T.E.

"Hierarchical Control System Emulation Applications Guide," NBS-GCR-82-410, January 1985

JONES, Albert

Albus, J.S., Barkmeyer, E. and Jones, A.

"Approach to a System Architecture for Post Office Automation," Proceedings of the USPS 4th Advanced Technology Conference, Automation Technology Workshop, Washington, DC, November 5-7, 1990

JUBERTS, Maris

Kilmer, R.D., McCain, H.G., Juberts, M. and Legowik, S.A.

"Watchdog Safety Computer Design and Implementation," Proceedings of the SME Robots 8 Conference and Exposition, Detroit, MI, June 4-7, 1984

Szabo, S., Juberts, M. and Kilmer, R.D.

"Automated Guided Vehicles at the National Bureau of Standards Automatic Manufacturing Research Facilty," Journal of Unmanned Vehicle Systems, pgs 38-47, Summer 1984

Dainis, A. and Juberts, M.

"Accurate Remote Measurement of Robot Trajectory Motion," Proceedings of the IEEE International Conference on Robotics and Automation, St. Louis, MI, March 1985

Albus, J.S., Juberts, M. and Szabo, S.

"RCS: A Reference Model Architecture for Intelligent Vehicle and Highway Systems," Proceedings of the 25th Silver Jubilee International Symposium on Automotive Technology and Automation, Florence, Italy, June 1-5, 1992

Murphy, K., Juberts, M., Legowik, S., Nashman, M., Schneiderman, H., Scott, H. and Szabo, S.

"Ground Vehicle Control at NIST: from Teleoperation to Autonomy," Published at the Seventh Annual Space Operations, Applications, and Research Symposium, Houston, TX, August 3-5, 1993

Juberts, M., Murphy, K., Nashman, M., Scheiderman, H., Scott, H. and Szabo, S. "Development and Test Results for a Vision-Based Approach to AVCS," Proceedings of the 26th International Symposium on Automotive Technology and Automation, Aachen, Germany, September 1993

KANADE, Takeo

Herman, M., Kanade, T. and Kuroe, S.

"Incremental Acquisition of a Three-Dimensional Scene Model from Images," Proceedings of the IEEE Transactions on Pattern Analysis and Machine Intelligence, Vol. PAMI-6, No. 3, May 1984

Herman, M. and Kanade, T.

"Incremental Reconstruction of 3D Scenes from Multiple Complex Images," Artifical Intelligence, Vol. 30, No. 3, pgs 289-341, December 1986

Walker, E.L., Herman, M. and Kanade, T.

"Framework for Representing and Reasoning about Three-Dimensional Objects for Vision," AI Magazine, Vol. 9, No. 2. pgs 47-58, October 1987

KELMAR, Laura

Kelmar, L.

"Manipulator Servo Level World Model," NISTTN 1258, Gaithersburg, MD, December 1989

Kelmar, L.

"Manipulator Primitive Level World Modeling," NISTTN 1273, Gaithersburg, MD, December 1989

Chaconas, K., Kelmar, L. and Nashman, M.

"NASREM Implementation of Position Determination from Motion," NISTIR 90-4293, Gaithersburg, MD, April 1990

Kelmar, L. and Lumia, R.

"World Modeling for Sensory Interactive Trajectory Generation," Proceedings of the IEEE Third International Symposium on Robotics and Manufacturing (ISRAM 90), Burnaby, British Columbia, Canada, July 18-20, 1990

Kelmar, L. and Lumia, R.

"Sensory Interactive Robot Trajectory Control Using a Real-Time World Model," Journal of Intelligent and Robotic Systems, Vol. 5, pgs 39-47, 1992

KENT, Ernest W.

Albus, J.S., Kent, E., Nashman, M., Mansbach, P., Palombo, L. and Shneier, M.O. "Six-Dimensional Vision System." SPIE Vol 336 Robot Vision, May 1982

Furlani, C.M., Kent, E.W., Bloom, H.M. and Mclean, C.R.

"Automated Manufacturing Research Facility of the National Bureau of Standards," Summer Computer Simulation Conference, Vancouver, British Columbia, Canada, July 11-13, 1983

Kent, E.W.

"Hierarchical Control of Robot Vision by Internal Models," Proceedings of the Second Annual Control Engineering, Rosemont, II, 1983

Kent, E.W. and Albus, J.S.

"Servoed World Models as Interfaces Between Robot Control Systems and Sensory Data," Robotica, Vol. 2, No. 1, pgs 17-25, January 1984

Albus, J.S., Barbera, A.J., Fitzgerald, M.L., **Kent, E.W.**, Scott, H.A. and Kilmer, R.D. "A Control System for an Automated Manufacturing Research Facility," Proceedings of the Robots 8 Conference and Exposition, Volume 2 - Future Considerations, Detroit, MI, June 4-7, 1984

Shneier, M.O., Kent, E.W. and Mansbach, P.

"Representing Workspace and Model Knowledge for a Robot with Mobile Sensors," Proceedings of the 7th International Conference on Pattern Recognition, Montreal, Canada, July 1984

Kent, E.W., Shneier, M.O., Lumia, R., Herriman, M., Luck, R.L. and Henrici, G.S. "Architecture of the NBS Pipelined Image Processing Engine," Conference on Algorithm-Guide Parallel Architectures for Automatic Target Recognition, Leesburg, VA, 1984

Lumia, R., Shneier, M.O. and Kent, E.W.

"Real-Time Iconic Image Processor," Proceedings of the IEEE International Conference on Robotics and Automation, St. Louis, MO, March 1985

Kent, E.W. and Tanimoto, S.L.

"Hierarchical Cellular Logic and the Pipe Processor: Structural and Functional Correspondence," IEEE Computer Society Workshop on Computer Architecture for Pattern Analysis and Image Database Management - Capaidm, Miami Beach, FL, July 1985

Kent, E.W., Shneier, M.O. and Lumia, R.

"Pipe," Journal of Parallel and Distributed Computing, 1985

Kent, E.W., Wheatley, T.E. and Nashman, M.

"Real-Time Cooperative Interaction between Structured-Light and Reflectance Ranging for Robot Guidance," Robotica, Volume 3, pgs 7-11, 1985

Shneier, M.O., Lumia, R. and Kent, E.W.

"Model-Based Strategies for High-Level Robot Vision," Computer Vision, Graphics and Image Processing, pgs 293-306, March 1986

Kent, E.W., Shneier, M.O. and Hong, T.H.

"Building Representations From Fusion of Multiple Views," Proceedings of the IEEE International Conference on Robotics and Automation, San Francisco, CA, April 7-10, 1986

KILLOUGH, S.M.

Corbett, G.K., Killough, S.M., Richardson, B.S. and Herman, M.

"Human Factors Testbed for Ground-Vehicle Telerobotics Research," Proceedings of the IEEE Southeast Conference '90, New Orleans, LA, April 1-4, 1990

KILMER, Roger D.

Kilmer, R.D.

"Safety Sensor System for Industrial Robots," Proceedings of the Robots IV Conference and Exposition, Detroit, MI, March 2-4, 1982

Kilmer, R.D., McCain, H.G., Juberts, M. and Legowik, S.A.

"Watchdog Safety Computer Design and Implementation," Proceedings of the SME Robots 8 Conference and Exposition, Detroit, MI, June 4-7, 1984

Albus, J.S., Barbera, A.J., Fitzgerald, M.L., Kent, E.W., Scott, H.A. and Kilmer, R.D.

"A Control System for an Automated Manufacturing Research Facility," Proceedings of the Robots 8 Conference and Exposition, Volume 2 - Future Considerations, Detroit, MI, June 4-7, 1984

Szabo, S., Juberts, M. and Kilmer, R.D.

"Automated Guided Vehicles at the National Bureau of Standards Automatic Manufacturing Research Facilty," Journal of Unmanned Vehicle Systems, pgs 38-47, Summer 1984

McCain, H.G., Kilmer, R.D. and Murphy, K.N.

"Development of a Cleaning and Deburring Workstation for the AMRF," Proceedings of the Deburring and Surface Conditioning '85 Conference, July 1985

McCain, H.G., Kilmer, R.D., Szabo, S. and Abrishamian, A.

"Hierarchically Controlled Autonomous Robot for Heavy Payload Military Field Applications," Proceedings of the International Conference on Intelligent Autonomous Systems, Amsterdam, The Netherlands, December 1986

Leake, S.A. and Kilmer, R.D.

"The NBS Real-time Control System User's Reference Manual," NISTTN 1250, Gaithersburg, MD, August 1988

Szabo, S., Scott, H.A. and Kilmer, R.D.

"Control System Architecture for the Team Program," Proceedings of the Second International Symposium on Robotics and Manufacturing Research Education and Applications, Alburqurque, NM, November 16-18, 1988

Albus, J.S., Quintero, R., Lumia, R., Herman, M., Kilmer, R. and Goodwin, K. "Concept for a Reference Model Architecture for Real-Time Intelligent Control Systems (ARTICS)," NISTTN 1277, Gaithersburg, MD, April 1990

Norcross, R.J., Bunch, W.R. and Kilmer, R.D.

"AMRF Composite Fabrication Workstation," Proceedings of the IEEE Third International Symposium on Robotics & Manufacturing (ISRAM), Burnaby, British Columbia, Canada, July, 18-20, 1990

Szabo, S., Scott, H.A. and Kilmer, R.D.

"Control System Architecture for Unmanned Ground Vehicles," Proceedings of the AUVS-90, Dayton, OH, July 30-August 1, 1990

Albus, J.S., Quintero, R., Lumia, R., Herman, M., Kilmer, R. and Goodwin, K. "A Reference Model Architecture for ARTICS," ASME Manufacturing Review, Vol. 4, No. 3, September 1991

KRAMER, Thomas R.

Kramer, T.R.

"Issues Concerning Material Removal Shape Element Volumes (MRSEVs)," NISTIR 4804, Gaithersburg, MD, March 1992

Kramer, T.R.

"A Library of Material Removal Shape Element Volumes [MRSEVs]," NISTIR 4809, Gaithersburg, MD, March 1992

Proctor, F.M., Michaloski, J. and Kramer, T.

"A Methodology for Integrating Sensor Feedback in Machine Tool Controllers," Proceedings of the Second International Conference on Flexible Automation and Information Management, Washington, DC, June 30, 1992

Kramer, T. R., Morris, K.C. and Sauder, D.A.

"A Structural EXPRESS Editor," NISTIR 4903, Gaithersburg, MD, August, 1992

Kramer, T.

"Pocket Milling with Tool Engagement Detection," Journal of Manufacturing Systems, Vol. 11, No. 2, pgs 114-123, 1992

Kramer, T.R. and Senehi, M.K.

"Feasibility Study: Reference Architecture for Machine Control Systems Integration," NISTIR 5297, Gaithersburg, MD, November 1993

KUROE, Shigeru

Herman, M., Kanade, T. and Kuroe, S.

"Incremental Acquisition of a Three-Dimensional Scene Model from Images," Proceedings of the IEEE Transactions on Pattern Analysis and Machine Intelligence, Vol. PAMI-6, No. 3, May 1984

LAU, Herbert

Lau, H., Hong, T.H. and Herman, M.

"Optimal Estimation of Optical Flow, Time-to-contact and Depth," NISTIR 4919, Gaithersburg, MD, September 1992

LAU, Kam

Lau, K., Hocken, R. and Haynes, L.

"Robot Performance Measurements Using Automatic Laser Techniques," NBS-Navy NAV/CIM Workshop on Robot Standards, Detroit, MI, June 6-7, 1985

Dagalakis, N.G. and Lau, K.C.

"Optical Sensors for Robot Performance Testing and Calibration," Vision, Vol. 5, No. 3, pgs 10-14, Winter 1988

LEAKE, Stephen A.

Leake, S.

"Robot Sensor Language," Proceedings of the 1987 Goddard Conference on Space Applications of Artificial Intelligence and Robotics, GSFC, Greenbelt, MD, May 13-14, 1987

Leake, S.

"Comparison of Ada and C on Sun and Microvax," Proceedings of 11th IASTED International Symposium on Robotics and Automation, Santa Clara, CA, May 25-27, 1988

Leake, S.A. and Kilmer, R.D.

"The NBS Real-time Control System User's Reference Manual," NISTTN 1250, Gaithersburg, MD, August 1988

Leake, S.

"Hierarchical Ada Robot Programming System (HARPS): A Complete and Working Telerobot Control System Based on the NASREM Model," Proceedings of the 1989 IEEE International Conference on Robotics and Automation, Scottsdale, AZ, May 14-19, 1989

LEE, James D.

Lee, J.D. and Haynes, L.S.

"Finite-Element Analysis of Flexible Fixturing System," Journal of Engineering for Industry, May 1987

Lee, J.D., Haynes, L.S., Wang, B.L. and Tsai, T.M.

"Control of Flexible Robot Arm," Modelings and Control of Robotic Manipulators and Manufacturing Processes, SME, pgs 241-251, 1987

Lee, J.D.

"Finite Element Procedures of Elastic-Plastic Solids at Large Strain," Journal of Engineering for Industry, Vol. 109, pgs 134-139, 1987

Dagalakis, N.G., Albus, J.S., Wang, B.L., Unger, J. and Lee, J.D.

"Stiffness Study of a Parallel Link Robot Crane for Shipbuilding Applications," Proceedings of the 7th International Conference for Offshore Mechanical and Arctic Engineering, Houston, TX, February 7-12, 1988

Albus, J.S., Dagalakis, N.G., Wang, B.L., Unger, J., Lee, J.D. and Yancey, C.W. "Available Robotics Technology for Applications in Heavy Industry," 1988 Iron and Steel Exposition and Annual Convention, Houston, TX, February 7-12, 1988

Lee, J.D., Albus, J.S., Dagalakis, N.G. and Tsai, T.M.

"Computer Simulation of a Parallel Link Manipulator," Robotics and Computer Integrated Manufacturing, August 1988

Unger, J., Dagalakis, N.G., Tsai, T.M. and Lee, J.D.

"Optimum Stiffness Study for a Parallel Link Robot Crane under Horizontal Force," Proceedings of the Second International Symposium on Robotics and Manufacturing Research, Education, and Applications, Albuquerque, NM, November 16-18,1988

Lee, J.D.

"Finite Element Analysis for Large Strain Elastic-Plastic Theories," Computers and Structures, Published in Great Britian, Vol. 28, No. 3, pgs 395-406, 1988

Lee, J.D., Albus, J.S., Dagalakis, N.G. and Tsai, T.M.

"Performance Measures of a Robotic Micropositioner," Proceedings of the 2nd International Symposium on Robotics and Manufacturing ASME, pgs 1047-1056, 1988

Lee, J.D. and Wang, B.L.

"Optimal Control of a Flexible Robot Arm," Computers and Structures, Vol. 29, No. 3, pgs 459-467, 1988

Lee, J.D. and Wang, B.L.

"Dynamic Equations for a Two-Link Flexible Robot Arm," Computers and Structures, Vol. 29, No. 3, pgs 469-477, 1988

Dagalakis, N.G., Albus, J.S., Goodwin, K.R., Lee, J.D., Tsai, T.M., Abrishamian, A., Bostelman, R. and Yancey, C.

"Robot Crane Technology (Final Report)," NISTTN 1267, Gaithersburg, MD, July 1989

LEGOWIK, Steven A.

Kilmer, R.D., McCain, H.G., Juberts, M. and Legowik, S.A.

"Watchdog Safety Computer Design and Implementation," Proceedings of the SME Robots 8 Conference and Exposition, Detroit, MI, June 4-7, 1984

Szabo, S., Scott, H.A., Murphy, K.N. and Legowik, S.A.

"Control System Architecture for a Remotely Operated Unmanned Land Vehicle," Proceedings of the 5th IEEE International Symposium on Intelligent Control, Philadelphia, PA, September 1990 Szabo, S., Murphy, K.N., Scott, H.A., Legowik, S.A. and Bostelman, R.V. "Control System Architecture for Unmanned Land Vehicles," Proceedings of the Association for Unmanned Vehicle Systems, Huntsville, AL, June 21-24, 1992

Szabo, S., Scott, H.A., Murphy, K.N., **Legowik, S.A.** and Bostelman, R.V. "High-Level Mobility Controller for a Remotely Operated Unmanned Land Vehicle," Journal of Intelligent and Robotic System, Vol. 5, pgs 63-77, 1992

Murphy, K., Juberts, M., Legowik, S., Nashman, M., Schneiderman, H., Scott, H. and Szabo, S.

"Ground Vehicle Control at NIST: from Teleoperation to Autonomy," Published at the Seventh Annual Space Operations, Applications, and Research Symposium, Houston, TX, August 3-5, 1993

LI, W.X.

Roche, M. and Li, W. X.

"Note on Real Time Parametric Cubic Segment Curve Generation," Intelligent Instruments and Computers, Vol. 5, No. 7, pgs 168-174, July 1987

Roche, M. and Li, W.

"Real Time Generation of Smooth Curves using Local Cubic Segments," ACCESS, Vol. 7, No. 6, November 1988

LIU, Hongche

Liu, H., Hong, T.H., Herman, M. and Chellappa, R.

"A Reliable Optical Flow Algorithm Using 3-D Hermite Polynomials," University of Maryland, Center for Automation Research Technical Report, College Park, MD, November 1993

Liu, H., Hong, T., Herman, M. and Chellappa, R.

"A Reliable Optical Flow Algorithm Using 3-D Hermite Polynomials," NISTIR 5333, Gaithersburg, MD, December 1993

LOWENFELD, E.

Nagel, R.N., VanderBrug, G.J., Albus, J.S. and Lowenfeld, E.

"Experiments In Part Acquisition Using Robot Vision," Proceedings of the Autofact II, Robots IV Conference, Detroit, MI, October 29 - November 1, 1979

LUCK, R.L.

Kent, E.W., Shneier, M.O., Lumia, R., Herriman, M., Luck, R.L. and Henrici, G.S. "Architecture of the NBS Pipelined Image Processing Engine," Conference on Algorithm-Guide Parallel Architectures for Automatic Target Recognition, Leesburg, VA, 1984

Rangachar, R., Hong, T., Herman, M., Luck, R. and Lupo, J. "Real-Time Differential Range Estimation Based on Time-Space Imagery Using Pipe," Proceedings of the SPIE Real-Time Image Processing II: Algorithms, Architectures, & Applications, Vol. 1295, Orlando, FL, April 1990

Rangachar, R., Hong, T.H., Herman, M. and Luck R.

"Analysis of Optical Flow Estimation Using Epipolar Plane Images," Proceedings of the SPIE Advances in Intelligent Systems: Intelligent Robots and Computer Vision, Boston, MA, November 1990

Rangachar, R., Hong, T.H., Herman, M. and Luck, R.

"Analysis of Optical Flow Estimation Using Epipolar Plane Images," NISTIR 4569, Gaithersburg, MD, April 1991

Rangachar, R., Hong, T.H., Herman, M. and Luck, R.

"Three Dimensional Reconstruction From Optical Flow Using Temporal Integration," NISTIR 4570, Gaithersburg, MD, April 1991

LUMIA, Ronald

Kent, E.W., Shneier, M.O., Lumia, R., Herriman, M., Luck, R.L. and Henrici, G.S.

"Architecture of the NBS Pipelined Image Processing Engine," Conference on Algorithm-Guide Parallel Architectures for Automatic Target Recognition, Leesburg, VA, 1984

Lumia, R., Shneier, M.O. and Kent, E.W.

"Real-Time Iconic Image Processor," Proceedings of the IEEE International Conference on Robotics and Automation, St. Louis, MO, March 1985

Lumia, R.

"Representing Solids for a Real-Time Robot Sensory System," Proceedings of the Prolamat '85 Conference, Paris, France, June 1985

Kent, E.W., Shneier, M.O. and Lumia, R.

"Pipe," Journal of Parallel and Distributed Computing, 1985

Shneier, M.O., Lumia, R. and Kent, E.W.

"Model-Based Strategies for High-Level Robot Vision," Computer Vision, Graphics and Image Processing, pgs 293-306, March 1986

Albus, J.S., Lumia, R. and McCain, H.G.

"Hierarchical Control of Intelligent Machines Applied to Space Station Telerobots," Proceedings of the 1987 IEEE International Symposium on Intelligent Control, Philadelphia, PA, January 19-20, 1987

Shneier, M.O., Lumia, R. and Herman, M.

"Prediction-Based Vision for Robot Control," Computer Magazine, pgs 46-55, February 1987

Lumia, R. and Albus, J.S.

"Architecture to Support Teleoperation and Autonomy," Proceedings of the 1987 IEEE Conference on Systems, Man, and Cybernetics, Alexandria, VA, October 20-23,1987

Fiala, J.C., Lumia, R. and Albus, J.S.

"Servo Level Algorithms for the NASREM Telerobot Control System Architecture," SPIE Volume 851, Proceedings of SPIE 1987 Cambridge Symposium of Advances Intelligent Robotic Systems, Cambridge, MA, November 2-4, 1987

Lumia, R. and Albus, J.S.

"Teleoperation and Autonomy for Space Robotics," Robotics, Vol. 4, No. 1, pgs 27-33, Elsevier Science Publishers B.V. (North-Holland), March 1988

Michaloski, J.L., Wheatley, T.E. and Lumia, R.

"Exploiting Computational Parallelism with a Hierarchical Robot Control System," IEEE Journal of Robotics and Automation, April 1988

Lumia, R.

"CAD-Based Off-Line Programming Applied to a Cleaning and Deburring Workstation," Proceedings of the NATO Workshop on CAD-Based Robots, Il Ciocco, Italy, July 1988

Lumia, R., Fiala, J.C. and Wavering, A.J.

"Architecture to Support Autonomy, Teleoperation, and Shared Control," Proceedings of the IEEE Conference on Systems, Man, and Cybernetics, Beijing, China, August 5-10, 1988

Michaloski, J.L., Lumia, R. and Wheatley, T.E.

"Heuristics for Robot System Design Using a Concurrent Hierarchical Control Model," Robot Systems Division Internal Report, National Institute of Standards and Technology, Gaithersburg, MD, September 1988

Lumia, R. and Albus, J.S.

"Space Robotics: Evolution and Applications," Paper Number 88-1640, Proceedings of the Instrument Society of America 88 International Conference, Houston, TX, October 16-21, 1988

Lumia, R., Fiala, J. and Wavering, A.

"NASREM: Robot Control System and Testbed," Proceedings of the Second International Symposium on Robotics and Manufacturing Research, Education, and Applications, Alburquerque, NM, November 16-18, 1988

Tarnoff, N. and Lumia, R.

"Role of Off-Line Robot Programming in Hierarchical Control," Proceedings of Second International Symposium Robotics and Manufacturing Research, Education, and Applications, Albuquerque, NM, November 16-18, 1988

Lumia, R. and Wavering, A.J.

"Trajectory Generation for Space Telerobots," Proceedings of the 1989 Conference on Space Telerobotics, Pasadena, CA, January 31 - February 2, 1989

Lumia, R. and Fiala, J.

"Flight Telerobotic Servicer: From Functional Architecture to Computer Architecture," Proceedings of the 1989 Conference on Space Telerobotics, Pasadena, CA, January 31 - February 2, 1989

Albus, J.S., McCain, H.G. and Lumia, R.

"NASA/NBS Standard Reference Model for Telerobot Control System Architecture (NASREM)," NISTTN 1235, 1989 Ed, Gaithersburg, MD, April 1989 (supersedes NBS Technical Note 1235, July 1987)

Lumia, R.

"NASREM as a Functional Architecture for the Design of Robot Control Systems," Proceedings of the NATO's Advanced Research Workshop on Sensors, Maratea, Italy, August 26 - September 3, 1989

Lumia, R.

"Sensor-Based Robot Control Requirements for Space," Proceedings of the NATO's Advanced Researchg Workshop on Sensors, Maratea, Italy, August 26 - September 3, 1989

Albus, J.S., Lumia, R., Fiala, J. and Wavering, A.

"NASREM -- The NASA/NBS Standard Reference Model for Telerobot Control System Architecture," Proceedings of the 20th International Symposium on Industrial Robots, Tokyo, Japan, October 4-6, 1989

Lumia, R., Fiala, J.C. and Wavering, A.J.

"NASREM Robot Control System Standard," Robotics & Computer-Integrated Manufacturing, Vol. 6, No. 4, pgs 303-308, November 1989

Michaloski, J.L., Wheatley, T.E. and Lumia, R.

"Analysis of Computational Parallelism with a Concurrent Hierarchical Robot Control System," NISTIR 90-4251, Gaithersburg, MD, March 1990

Albus, J.S., Quintero, R., Lumia, R., Herman, M., Kilmer, R. and Goodwin, K. "Concept for a Reference Model Architecture for Real-Time Intelligent Control Systems (ARTICS)," NISTTN 1277, Gaithersburg, MD, April 1990

Fiala, J.C. and Lumia, R.

"Approach to Telerobot Computing Architecture," NISTIR 4357, Gaithersburg, MD, June 1990

Kelmar, L. and Lumia, R.

"World Modeling for Sensory Interactive Trajectory Generation," Proceedings of the IEEE Third International Symposium on Robotics and Manufacturing (ISRAM 90), Burnaby, British Columbia, Canada, July 18-20, 1990

Tarnoff, N., Jacoff, A. and Lumia, R.

"World Model Registration for Effective Off-Line Programming of Robots," Proceedings of the IEEE Third International Symposium on Robotics and Manufacturing (ISRAM 90), Burnaby, British Columbia, Canada, July 18-20,1990

Lumia, R.

"Short Term Evolution for the Flight Telerobotic Servicer," NISTIR 4463, Gaithersburg, MD, November 1990

Lumia, R.

"Evolution of the Flight Telerobotic Servicer," Proceedings of the International Symposium on Artificial Intelligence, Robotics & Automation in Space (I-SAIRAS '90), Kobe, Japan, November 1990

Albus, J.S., Quintero, R., Lumia, R., Herman, M., Kilmer, R. and Goodwin, K.

"A Reference Model Architecture for ARTICS," ASME Manufacturing Review, Vol. 4, No. 3, September 1991

Fiala, J.C. and Lumia, R.

"Adaptive Inertia Compensation Using a Cerebellar Model Algorithm," Proceedings of the International Joint Conference on Neural Networks, Singapore, November 18-21, 1991

Fiala, J., Wavering, A. and Lumia, R.

"A Manipulator Control Testbed: Implementation and Applications," Proceedings of the 15th Annual AAS Guidance and Control Conference, Keystone, CO, February 8-12, 1992

Fiala, J. and Lumia, R.

"The Effect of Time-Delay and Discrete Control on the Contact Stability of Simple Position Controllers," Proceedings of the 1992 IEEE International Conference on Robotics and Automation, Nice, France, May 10-15, 1992

Lumia, R.

"Design Methodology for NASREM Software Development," Proceedings of the ISRAM '92 Conference, Santa Fe, NM, November 10-12, 1992

Lumia, R.

"Integrating New Sensors into a NASREM Implementation," Proceedings of ISRAM '92 Conference, Santa Fe, NM, November 10-12, 1992

Lumia, R.

"Using NASREM for Real-Time Sensory Interactive Robot Control," Robotica Magazine (special issue), 1992

Kelmar, L. and Lumia, R.

"Sensory Interactive Robot Trajectory Control Using a Real-Time World Model," Journal of Intelligent and Robotic Systems, Vol. 5, pgs 39-47, 1992

Tarnoff, N., Jacoff, A. and Lumia, R.

"Graphical Simulation for Sensor-Based Robot Programming," Journal of Intelligent and Robotic Systems, Vol. 5, pgs 49-62, 1992

Wavering, A.J., Fiala, J.C., Roberts, K.J. and Lumia, R.

"TRICLOPS: A High-Performance Trinocular Active Vision System," Proceedings of the IEEE Conference on Robotics and Automation, Atlanta, GA, May 2-6, 1993

Schneiderman, H., Nashman, M. and Lumia, R.

"Model-based vision for car following," Proceedings of the SPIE Sensor Fusion VI, Boston, MA, September 1993

Wavering, A.J. and Lumia, R.

"Predictive visual tracking," Proceedings of the SPIE Intelligent Robots and Computer Vision XII, Boston, MA, September 7-10, 1993

Fiala, J.C., Lumia, R., Roberts, K.J. and Wavering, A.J.

"TRICLOPS: A Tool for Studying Active Vision," Submitted to International Journal of Computer Vision

Lumia, R.

"Using NASREM for Telerobot Control System Development," To be published in Robotica, 1994

LUPO, Jasper

Rangachar, R., Hong, T., Herman, M., Luck, R. and Lupo, J.

"Real-Time Differential Range Estimation Based on Time-Space Imagery Using Pipe," Proceedings of the SPIE Real-Time Image Processing II: Algorithms, Architectures, & Applications, Vol. 1295, Orlando, FL, April 1990

Rangachar, R., Hong, T., Herman, M. and Lupo, J.

"Real-Time Implementation of a Differential Range Finder," Proceedings of the SPIE Real-Time Image Processing II: Algorithms, Architectures. & Applications, Vol. 1295, Orlando, FL, April 1990

MANHEIMER, Kenneth L.

Manheimer, K.L., Clark, S.N., Warsaw, B.A. and Rowe, W.P.

"The Depot: A Framework for Sharing Software Installation Across Organizational and UNIX Platform Boundaries," NISTIR 4436, Gaithersburg, MD, September 1990

MANSBACH, Peter

Albus, J.S., Kent, E., Nashman, M., Mansbach, P., Palombo, L. and Shneier, M.O. "Six-Dimensional Vision System." SPIE Vol 336 Robot Vision, May 1982

Shneier, M.O., Kent, E.W. and Mansbach, P.

"Representing Workspace and Model Knowledge for a Robot with Mobile Sensors," Proceedings of the 7th International Conference on Pattern Recognition, Montreal, Canada, July 1984

Mansbach, P.

"Calibration of a Camera and Light Source by Fitting to a Physical Model," Computer Vision, Graphics, and Image Processing 35, pgs 200-219, 1986

Mansbach, P. and Shneier, M.

"Gramps Operating System: User's Guide," NBSIR 88-3778, Gaithersburg, MD, September 1988

Mansbach, P.

"Gramps Multiprocessor Operating System," NISTIR 89-4190, Gaithersburg, MD, October 1988

MCCAIN, Harry G.

Kilmer, R.D., McCain, H.G., Juberts, M. and Legowik, S.A.

"Watchdog Safety Computer Design and Implementation," Proceedings of the SME Robots 8 Conference and Exposition, Detroit, MI, June 4-7, 1984

Haynes, L.S., Barbera, A.J., Albus, J.S., Fitzgerald, M.L. and McCain, H.G.

"Application Example of the NBS Robot Control System," Robotics and Computer Integrated Manufacturing, Vol. 1, No. 1, pgs 81-95, 1984

McCain, H.G.

"Hierarchical Controlled, Sensory Interactive Robot in the Automated Manufacturing Research Facility," Proceedings of the IEEE International Conference on Robotics and Automation, St. Louis, MO, March 25-26, 1985

McCain, H.G., Kilmer, R.D. and Murphy, K.N.

"Development of a Cleaning and Deburring Workstation for the AMRF," Proceedings of the Deburring and Surface Conditioning '85 Conference, July 1985

McCain, H.G., Kilmer, R.D., Szabo, S. and Abrishamian, A.

"Hierarchically Controlled Autonomous Robot for Heavy Payload Military Field Applications," Proceedings of the International Conference on Intelligent Autonomous Systems, Amsterdam, The Netherlands, December 1986

Albus, J.S., Lumia, R. and McCain, H.G.

"Hierarchical Control of Intelligent Machines Applied to Space Station Telerobots," Proceedings of the 1987 IEEE International Symposium on Intelligent Control, Philadelphia, PA, January 19-20, 1987

Albus, J.S., McCain, H.G. and Lumia, R.

"NASA/NBS Standard Reference Model for Telerobot Control System Architecture (NASREM)," NISTTN 1235, 1989 Ed, Gaithersburg, MD, April 1989 (supersedes NBS Technical Note 1235, July 1987)

MCLEAN, Charles R.

Albus, J.S., Mclean, C.R., Barbera, A.J. and Fitzgerald, M.L.

"Architecture for Real-Time Sensory-Interactive Control of Robots in a Manufacturing Facility," Proceedings of the Fourth IFAC/IFIP Symposium -- Information Control Problems in Manufacturing Technology, Gaithersburg, MD, October 26-28, 1982

Albus, J.S., Mclean, C.R., Barbera, A.J. and Fitzgerald, M.L.

"Hierarchical Control for Robots in an Automated Factory," Proceedings of the 13th International Symposium on Industrial Robots/Robots 7, Chicago, IL, April 18-21, 1983

Mclean, C., Mitchell, M. and Barkmeyer, E.

"Computer Architecture for Small-Batch Manufacturing," IEEE Spectrum, May 1983

Furlani, C.M., Kent, E.W., Bloom, H.M. and Mclean, C.R.

"Automated Manufacturing Research Facility of the National Bureau of Standards," Proceedings of the Summer Computer Simulation Conference, Vancouver, British Columbia, Canada, July 11-13, 1983

Albus, J.S., Mclean, C.R., Barbera, A.J. and Fitzgerald, M.L.

"Hierarchical Control for Robots and Teleoperators," Proceedings of the IEEE Workshop on Intelligent Control 1985, Rensselaer Polytechnic Institute, Albany, NY, August 1985

MEYSTEL, A.

Albus, J., Meystel, A. and Uzzaman, S.

"Nested Motion Planning for an Autonomous Robot," Proceedings of the IEEE Regional Conference on Aerospace Control Systems, Westlake Village, CA, May 25-27, 1993

MICHALOSKI, John L.

Michaloski, J.L. and Warsaw, B.A.

"Robot Control System Based on Forth," Robotics Engineering, Vol. 8, No. 5, pgs 22-26, May 1986

Michaloski, J.L.

"Coordinated Joint Motion for an Industrial Robot," NBSIR 88-3735, Gaithersburg, MD, March 1988

Michaloski, J.L., Wheatley, T.E. and Lumia, R.

"Exploiting Computational Parallelism with a Hierarchical Robot Control System," IEEE Journal of Robotics and Automation, April 1988

Michaloski, J.L., Lumia, R. and Wheatley, T.E.

"Heuristics for Robot System Design Using a Concurrent Hierarchical Control Model," Robot Systems Division Internal Report, National Institute of Standards and Technology, Gaithersburg, MD, September 1988

Michaloski, J.L., Wheatley, T.E. and Lumia, R.

"Analysis of Computational Parallelism with a Concurrent Hierarchical Robot Control System," NISTIR 90-4251, Gaithersburg, MD, March 1990

Michaloski, J. and Wheatley, T.

"System Factors in Real-Time Hierarchical Control," NISTIR 4386, Gaithersburg, MD, August 1990

Michaloski, J. and Wheatley, T.

"Design Principles for a Real-Time Robot Control System," Proceedings of the IEEE International Conference on Systems Engineering, Pittsburgh, PA, August 1990

Wheatley, T.E. and Michaloski, J.

"Configuration and Performance Evaluation of a Real-Time Robot Control System: The Skeleton Approach," Proceedings of the IEEE International Conference on Systems Engineering, Pittsburgh, PA, August 1990

Warsaw, B. and Michaloski, J.

"The TROI [Telerobotic Operator Interface] User's Guide," NISTIR 4471, Gaithersburg, MD, January 1991

Michaloski, J.L. and Warsaw, B.

"TROI Real-Time Operator Interface Management System for the NASREM Architecture," Proceedings of the 4th Topical Meeting on Robotics and Remote Systems, February 1991

Proctor, F.M., Michaloski, J. and Kramer, T.

"A Methodology for Integrating Sensor Feedback in Machine Tool Controllers," Proceedings of the Second International Conference on Flexible Automation and Information Management, Washington, DC, June 30, 1992

Albus, J.S., Quintero, R., Proctor, F., Michaloski, J., Dagalakis, N. and Tarnoff, N. "NIST Support to the Next Generation Controller Program: 1991 Final Technical Report," NISTIR 4888, Gaithersburg, MD, August 1992

Stouffer, K., Michaloski, J., Russell, R. and Proctor, F.

"ADACS - An Automated System for Part Finishing," NISTIR 5171, Gaithersburg, MD, April 1993

Proctor, F. and Michaloski, J.

"Enhanced Machine Controller Architecture Overview," NISTIR 5331, Gaithersburg, MD, December, 1993

MILLIGAN S.D.

Johnson, T.L., Milligan, S.D. and Fortmann, T.E.

"Hierarchical Control System Emulation Applications Guide," NBS-GCR-82-410, January 1985

MITCHELL, Mary J.

Mclean, C., Mitchell, M. and Barkmeyer, E.

"Computer Architecture for Small-Batch Manufacturing," IEEE Spectrum, May 1983

MONTGOMERY, Raymond C.

Quintero, R., Montgomery, R.C. and Tchoryk, P.

"Autonomous Rendezvous and Docking Scenarios for the Development of Guidelines and Standards," Proceedings of the AIAA Space Programs and Technologies Conference and Exhibit, Huntsville, AL, September 21-23, 1993

MORRIS, Katherine C.

Kramer, T.R., Morris, K.C. and Sauder, D.A.

"A Structural EXPRESS Editor," NISTIR 4903, Gaithersburg, MD, August, 1992

MURPHY, Karl N.

McCain, H.G., Kilmer, R.D. and Murphy, K.N.

"Development of a Cleaning and Deburring Workstation for the AMRF," Proceedings of the Deburring and Surface Conditioning '85 Conference, July 1985

Murphy, K.N., Tanguy, P.S., Norcross, R. and Proctor, F.

"Cleaning and Deburring Workstation Operations Manual," NBSIR 88-3804, Gaithersburg, MD, June 1988

Murphy, K.N.

"Real-Time Control System Modifications for a Deburring Robot User's Reference Manual," NBSIR 88-3832, Gaithersburg, MD, August 1988

Murphy, K.N., Norcross, R.J. and Proctor, F.M.

"CAD Directed Robotic Deburring," Proceedings of the Second International Symposium on Robotics and Manufacturing Research, Education, and Applications, Albuquerque, NM, November 16-18, 1988

Proctor, F.M., Murphy, K.N. and Norcross, R.J.

"Automating Robot Programming in the Cleaning and Deburring Workstation of the AMRF," Proceedings of the SME Conference on Deburring and Surface Condition '89, San Diego, CA, February 13-16, 1989

Proctor, F.M. and Murphy, K.N.

"Advanced Deburring System Technology," Winter Annual Meeting of the American Society of Mechanical Engineers, San Francisco, CA, December 10-15, 1989

Murphy, K.N. and Proctor, F.M.

"An Advanced Deburring and Chamfering System," Proceedings of the IEEE Third International Symposium on Robotics & Manufacturing (ISRAM 90), Burnaby, British Columbia, Canada, July 18-20, 1990

Szabo, S., Scott, H.A., Murphy, K.N. and Legowik, S.A.

"Control System Architecture for a Remotely Operated Unmanned Land Vehicle," Proceedings of the 5th IEEE International Symposium on Intelligent Control, Philadelphia, PA, September 1990

Murphy, K.

"Navigation and Retro-Traverse on a Remotely Operated Vehicle," Proceedings of the IEEE Singapore International Conference on Intelligent Control and Instrumentation, Singapore, February 1992

Szabo, S., Murphy, K.N., Scott, H.A., Legowik, S.A. and Bostelman, R.V. "Control System Architecture for Unmanned Land Vehicles," Proceedings of the Association for Unmanned Vehicle Systems, Huntsville, AL, June 21-24, 1992

Szabo, S., Scott, H.A., **Murphy**, **K.N.**, Legowik, S.A. and Bostelman, R.V. "High-Level Mobility Controller for a Remotely Operated Unmanned Land Vehicle," Journal of Intelligent and Robotic System, Vol. 5, pgs 63-77, 1992

Murphy, K., Juberts, M., Legowik, S., Nashman, M., Schneiderman, H., Scott, H. and Szabo, S.

"Ground Vehicle Control at NIST: from Teleoperation to Autonomy," Published at the Seventh Annual Space Operations, Applications, and Research Symposium, Houston, TX, August 3-5, 1993

Herman, M., Szabo, S., Murphy, K., Coombs, D., Hong, T.H., Scott, H. and Dagalakis, N. "Recommendations for Performance Evaluation of Unmanned Ground Vehicle Technologies," NISTIR 5244, Gaithersburg, MD, August 1993

Juberts, M., Murphy, K., Nashman, M., Scheiderman, H., Scott, H. and Szabo, S. "Development and Test Results for a Vision-Based Approach to AVCS," Proceedings of the 26th International Symposium on Automotive Technology and Automation, Aachen, Germany, September 1993

Bostelman, R., Albus, J., Murphy, K., Tsai, T. and Amatucci, E. "A Stewart Platform Lunar Rover," Proceedings of the Space '94 Conference, Albuquerque, NM, February 28 - March 3, 1994

NAGALIA, S.

Shneier, M., Nagalia, S., Albus, J.S. and Haar, R.

"Visual Feedback for Robot Control," Proceedings of the International Workshop on Industrial Applications of Machine Vision, Research Triangle, NC, May 3-5, 1982

NAGEL, Roger N.

Nagel, R.N., VanderBrug, G.J., Albus, J.S. and Lowenfeld, E.

"Experiments In Part Acquisition Using Robot Vision," Proceedings of the Autofact II, Robots IV Conference, Detroit, MI, October 29 - November 1, 1979

Albus, J.S., Barbera, A., Fitzgerald, M.L., Nagel, R., VanderBrug, G. and Wheatley, T.E. "A Measurement and Control Model for Adaptive Robots," Proceedings of the 10th International Symposium on Industrial Robots, Milan, Italy, March 1980

Albus, J.S., Barbera, A.J. and **Nagel**, R.N. "Theory and Practice of Hierarchical Control," Proceedings of the 23rd IEEE Computer Society International Conference, Washington, DC, September 15-17, 1981

NASHMAN, Marilyn

Albus, J.S., Barbera, A.J., Fitzgerald, M.L. and Nashman, M.

"Sensory Interactive," Robots 31st General Assembly of the International Institution for Production Engineering Research, Toronto, Canada, September 1, 1981

Albus, J.S., Kent, E., Nashman, M., Mansbach, P., Palombo, L. and Shneier, M.O. "Six-Dimensional Vision System." SPIE Vol. 336 Robot Vision, May 1982

Kent, E.W., Wheatley, T.E. and Nashman, M.

"Real-Time Cooperative Interaction between Structured-Light and Reflectance Ranging for Robot Guidance," Robotica, Volume 3, pgs 7-11, 1985

Nashman, M.

"Low Level Robot Interface: The High Speed Host Interface," NBSIR 86-3393, Gaithersburg, MD, June 1986

Nashman, M. and Chaconas, K.J.

"NBS Vision System in the AMRF," NBSIR 87-3684, Gaithersburg, MD, December 1987

Hong, T.H., Nashman, M. and Chaconas, K.

"Image Compression Technology and Techniques," Internal Report, April 1988

Nashman, M. and Chaconas, K.J.

"Low Level Image Processing Techniques Using the Pipeline Image Processing Engine in the Flight Telerobotic Servicer," Proceedings of the 1988 Goddard Conference on Space Applications of Artificial Intelligence, Goddard Space Flight Center, Greenbelt, MD, May 1988

Nashman, M. and Chaconas, K.J.

"NBS Vision System in the AMRF," Journal of Research of the National Bureau of Standards, Vol. 93, No. 4, July 1988

Herman, M., Chaconas, K., Nashman, M. and Hong, T.H.

"Low Data Rate Remote Vehicle Driving," Proceedings of the 3rd IEEE International Symposium on Intelligent Control, Arlington, VA, August 24-26, 1988

Herman, M., Chaconas, K., Nashman, M. and Hong, T.H.

"Video Compression for Remote Vehicle Driving," Proceeding of the SPIE Advances in Intelligent Robotics Systems: Mobile Robots III, Vol. 1007, Cambridge, MA, November 1988

Chaconas, K.C. and Nashman, M.

"Visual Perception Processing in a Hierarchical Control System: Level 1," NISTTN 1260, Gaithersburg, MD, June 1989

Chaconas, K., Kelmar, L. and Nashman, M.

"NASREM Implementation of Position Determination from Motion," NISTIR 90-4293, Gaithersburg, MD, April 1990

Nashman, M. and Chaconas, K.

"Visual Perception Processing for the Flight Telerobotic Servicer Control System Level 1," Proceeding of the 1990 IEEE International Conference on Robotics and Automation, Cincinnati, OH, May 13-18, 1990

Nashman, M. and Chaconas, K.

"Three-Dimensional Position Determination from Motion," Proceedings of the SPIE Conference on Advances in Intelligent Systems, Boston, MA, November 1990

Chaconas, K. and Nashman, M.

"Real-Time Model-Based Tracking Combining Spatial and Temporal Features," NISTIR 4610, Gaithersburg, MD, June 1991

Chaconas, K.C. and Nashman, M.

"Model-Based Feature Tracking," Journal of Intelligent and Robotic Systems, 1991

Nashman, M.

"The Use of Vision and Touch Sensors for Dimensional Inspection Tasks," NISTIR 4839, Gaithersburg, MD, April 1992

Schneiderman, H. and Nashman M.

"Visual Processing for Autonomous Driving," Proceedings of the IEEE Workshop on Applications of Computer Vision, Palm Spring, CA, November 30-December 2, 1992

Nashman, M.

"The Use of Vision and Touch Sensors for Dimensional Inspection Tasks" The American Society of Mechanical Engineers, "Manufacturing Review," Vol. 6, No. 2, June 1993

Nashman, M. and Schneiderman, H.

"Real-Time Visual Processing for Autonomous Driving," Proceedings of the IEEE Intelligent Vehicles '93 Conference, Tokyo, Japan, July 14-16, 1993

Murphy, K., Juberts, M., Legowik, S., Nashman, M., Schneiderman, H, Scott, H. and Szabo, S.

"Ground Vehicle Control at NIST: from Teleoperation to Autonomy," Published at the Seventh Annual Space Operations, Applications, and Research Symposium, Houston, TX, August 3-5, 1993

Juberts, M., Murphy, K., Nashman, M., Scheiderman, H., Scott, H. and Szabo, S.

"Development and Test Results for a Vision-Based Approach to AVCS," Proceedings of the 26th International Symposium on Automotive Technology and Automation, Aachen, Germany, September 1993

Schneiderman, H., Nashman, M. and Lumia, R.

"Model-based vision for car following," Proceedings of the SPIE Sensor Fusion VI, Boston, MA, September 1993

Herman, M., Raviv, D., Schneiderman, H. and Nashman, M.

"Visual Road Following Without 3-D Reconstruction," Proceedings of the SPIE 22nd Applied Imagery Pattern Recognition Workshop, Vol. 2103, Washington, DC, October 1993

Schneiderman, H. and Nashman, M.

"Visual Tracking for Autonomous Driving," To be published in IEEE Transactions on Robotics and Automation

NORCROSS, Richard J.

Norcross, R.J.

"Control Structure for Multi-Tasking Workstations," Proceedings of the 1988 IEEE International Conference on Robotics and Automation, Philadelphia, PA, pgs 1133-1135, April 24-29, 1988

Murphy, K.N., Tanguy, P.S., Norcross, R. and Proctor, F.

"Cleaning and Deburring Workstation Operations Manual," NBSIR 88-3804, Gaithersburg, MD, June 1988

Murphy, K.N., Norcross, R.J. and Proctor, F.M.

"CAD Directed Robotic Deburring," Proceedings of the Second International Symposium on Robotics and Manufacturing Research, Education, and Applications, Albuquerque, NM, November 16-18, 1988

Norcross, R.J.

"Workstation Controller of the Cleaning and Deburring Workstation," NISTIR 89-4046, Gaithersburg, MD, February 1989

Proctor, F.M., Murphy, K.N. and Norcross, R.J.

"Automating Robot Programming in the Cleaning and Deburring Workstation of the AMRF," Proceedings of the SME Conference on Deburring and Surface Condition '89, San Diego, CA, February 13-16, 1989

Norcross, R.J., Bunch, W.R. and Kilmer, R.D.

"AMRF Composite Fabrication Workstation," Proceedings of the IEEE Third International Symposium on Robotics & Manufacturing (ISRAM), Burnaby, British Columbia, Canada, July, 18-20, 1990

Norcross, R.J.

"Fiber Placement Developments at the National Institute of Standards and Technology," Proceedings of the Conference on Composites in Manufacturing '92, Anaheim, CA, January 7-8, 1992

ORSER, Donald J.

Orser, D.J.

"Algebraic Representation for the Topology of Multicomponent Phase Diagrams," Chapter in "Computer Modeling of Phase Diagrams", Larry Bennett, Editor, ASM/TMS, Summer, 1986

Orser, D.J. and Roche, M.

"Extraction of Topographic Features in Support of Autonomous Underwater Vehicle Navigation," Proceedings of Fifth International Symposium of Unmanned, Untethered, Submersible Technology, Merrimack, NH, June 22-24, 1987

Raviv, D., Orser, D. and Albus, J.S.

"On Logarithmic Retinae," NISTIR 4807, Gaithersburg, MD, April 1992

Orser, D.J.

"Binocular Spherical Disparity: A Study in Representation for a Forward Translating Camera," NISTIR 4865, Gaithersburg, MD, June 1992

OSKARD, David N.

Herman, M., Hong, T.H., Swetz, S., Oskard, D. and Rosol, M.

"Planning and World Modeling for Autonomous Undersea Vehicles," Proceedings of the Third IEEE International Symposium on Intelligent Control, Arlington, VA, August 24-26, 1988

Oskard, D.N., Hong, T.H. and Shaffer, C.A.

"Real-Time Algorithms and Data Structures for Underwater Mapping," Proceedings of the SPIE Advances in Intelligent Robotics Systems Conference, Boston, MA, November 10-11, 1988

PALOMBO, L.

Albus, J.S., Kent, E., Nashman, M., Mansbach, P., **Palombo, L.** and Shneier, M.O. "Six-Dimensional Vision System." SPIE Vol 336 Robot Vision, May 1982

PROCTOR. Frederick M.

Murphy, K.N., Tanguy, P.S., Norcross, R. and Proctor, F.

"Cleaning and Deburring Workstation Operations Manual," NBSIR 88-3804, Gaithersburg, MD, June 1988

Proctor, F.M. and Tanguy, P.S.

"CAD Directed Automated Part Handling User's Reference Manual," NISTIR 88-3858, Gaithersburg, MD, September 1988

Murphy, K.N., Norcross, R.J. and Proctor, F.M.

"CAD Directed Robotic Deburring," Proceedings of the Second International Symposium on Robotics and Manufacturing Research, Education, and Applications, Albuquerque, NM, November 16-18, 1988

Proctor, F.M., Murphy, K.N. and Norcross, R.J.

"Automating Robot Programming in the Cleaning and Deburring Workstation of the AMRF," Proceedings of the SME Conference on Deburring and Surface Condition '89, San Diego, CA, February 13-16, 1989

Proctor, F.M. and Russell, R.

"Inventory of Equipment in the Cleaning and Deburring Workstation," NISTIR 89-4092, Gaithersburg, MD, May 1989

Proctor, F.M. and Russell, R.

"Recommended Technical Specifications for Procurement of Systems for a Cleaning and Deburring Workstation," NISTIR 89-4115, Gaithersburg, MD, June 1989

Proctor, F.M. and Murphy, K.N.

"Advanced Deburring System Technology," Winter Annual Meeting of the American Society of Mechanical Engineers, San Francisco, CA, December 10-15, 1989

Murphy, K.N. and Proctor, F.M.

"An Advanced Deburring and Chamfering System," Proceedings of the IEEE Third International Symposium on Robotics & Manufacturing (ISRAM 90), Burnaby, British Columbia, Canada, July 18-20, 1990

Proctor, F.

"Sensor-Based Real-Time Error Compensation," Proceedings of the International Control Engineering Exposition and Conference, Chicago, IL, February 24-26, 1992

Proctor, F.

"Controls and Sensors for Advanced Manufacturing," Proceedings of the International Manufacturing Technology Forum, Chicago, IL, June 4-5, 1992

Proctor, F.M., Michaloski, J. and Kramer, T.

"A Methodology for Integrating Sensor Feedback in Machine Tool Controllers," Proceedings of the Second International Conference on Flexible Automation and Information Management, Washington, DC, June 30, 1992

Albus, J.S., Quintero, R., **Proctor, F.**, Michaloski, J., Dagalakis, N. and Tarnoff, N. "NIST Support to the Next Generation Controller Program: 1991 Final Technical Report," NISTIR 4888, Gaithersburg, MD, August 1992

Stouffer, K., Michaloski, J., Russell, R. and Proctor, F.

"ADACS - An Automated System for Part Finishing," NISTIR 5171, Gaithersburg, MD, April 1993

Proctor, F.M., Damazo, B., Yang, C. and Frechette, S.

"Open Architectures for Machine Control," NISTIR 5307, Gaithersburg, MD, December 1993

Proctor, F. and Michaloski, J.

"Enhanced Machine Controller Architecture Overview," NISTIR 5331, Gaithersburg, MD, December, 1993

QUINTERO, Richard

Albus, J.S., Quintero, R., Huang, H.M. and Roche, M.

"Mining Automation Real-Time Control System Architecture Standard Reference Model (MASREM)," NISTTN 1261, Volume 1, Gaithersburg, MD, May 1989

Quintero, R.

"DoE/NIST Workshop on Common Architectures for Robotic Systems," National Institute of Standards and Technology Special Publication 784, April 1990

Albus, J.S., Quintero, R., Lumia, R., Herman, M., Kilmer, R. and Goodwin, K. "Concept for a Reference Model Architecture for Real-Time Intelligent Control Systems (ARTICS)," NISTTN 1277, Gaithersburg, MD, April 1990

Albus, J.S. and Quintero, R.

"Towards a Reference Model Architecture for Real-Time Intelligent Control Systems (ARTICS)," Proceedings of the IEEE Third International Symposium on Robotics and Manufacturing (ISRAM 90), Burnaby, British Columbia, Canada, July, 18-20, 1990

Huang, H.M. and Quintero, R.

"Task Decomposition Methodology for the Design of a Coal Mining Automation Hierarchical Real-Time Control System," Proceedings of the 5th IEEE International Symposium on Intelligent Control, Philadelphia, PA, September 5-7, 1990

Huang, H.M., Horst, J. and Quintero, R.

'Task Decomposition and Algorithm Development for Real-Time Motion Control of a Continuous Mining Machine," NISTIR 4596, Gaithersburg, MD, May 1991

Huang, H.M., Quintero, R. and Albus, J.S.

"A Reference Model, Design Approach, and Development Illustration toward Hierarchical Real-Time System Control for Coal Mining Operations," Advances in Control & Dynamic Systems, Academic Press, July 1991

Albus, J.S., Quintero, R., Lumia, R., Herman, M., Kilmer, R. and Goodwin, K. "A Reference Model Architecture for ARTICS," ASME Manufacturing Review, Vol. 4, No. 3, September 1991

Albus, J.S., Quintero, R., Proctor, F., Michaloski, J., Dagalakis, N. and Tarnoff, N. "NIST Support to the Next Generation Controller Program: 1991 Final Technical Report," NISTIR 4888, Gaithersburg, MD, August 1992

Quintero, R. and Barbera, A.J.

"A Real-Time Control System Methodology for Developing Intelligent Control Systems," NISTIR 4936, Gaithersburg, MD, October 1992

Quintero, R.

'Toward an Intelligent Control Systems Development Methodology," Position Paper for the JSGCC Software Initiative Workshop, Vail, CO, December 1-4, 1992

Huang, H.M., Hira, R., Quintero, R. and Barbera, A.

"Applying the NIST Real-Time Control System Reference Model to Submarine Automation: A Maneuvering System Demonstration," NISTIR 5126, Gaithersburg, MD, February 1993

Huang, H.M., Hira, R. and Quintero, R.

"A Submarine Maneuvering System Demonstration Based on the NIST Real-Time Control System Reference Model," Proceedings of the 8th IEEE International Symposium on Intelligent Control, Chicago, IL, August 24-27, 1993

Quintero, R. and Barbera, A.J.

"A Task Oriented Approach for Developing Complex Large-Scale Intelligent Control Systems Using Software Templates," Proceedings of the 8th IEEE International Symposium on Intelligent Control, Chicago, IL, August 24-27, 1993

Quintero, R., Montgomery, R.C. and Tchoryk, P.

"Autonomous Rendezvous and Docking Scenarios for the Development of Guidelines and Standards," Proceedings of the AIAA Space Programs and Technologies Conference and Exhibit, Huntsville, AL, September 21-23, 1993

Quintero, R. and Barbera, A.J.

"A Software Template Approach to Building Complex Large-Scale Intelligent Control Systems," Proceedings of the 8th IEEE International Symposium on Intelligent Control, Chicago, IL, September 25-27, 1993

Hira, R., Quintero, R., Goodwin, K. and Siewert, T.

"Report on Mobility for Welding Automation in Ship Construction," NISTIR 5301, Gaithersburg, MD, December 1993

RANGACHAR, Ramesh

Rangachar, R., Hong, T., Herman, M., Luck, R. and Lupo, J.

"Real-Time Differential Range Estimation Based on Time-Space Imagery Using Pipe," Proceedings of the SPIE Real-Time Image Processing II: Algorithms, Architectures, & Applications, Vol. 1295, Orlando, FL, April 1990

Rangachar, R., Hong, T., Herman, M. and Lupo, J.

"Real-Time Implementation of a Differential Range Finder," Proceedings of the SPIE Real-Time Image Processing II: Algorithms, Architectures. & Applications, Vol. 1295, Orlando, FL, April 1990

Rangachar, R., Hong, T.H., Herman, M. and Luck R.

"Analysis of Optical Flow Estimation Using Epipolar Plane Images," Proceedings of the SPIE Advances in Intelligent Systems: Intelligent Robots and Computer Vision, Boston, MA, November 1990

Rangachar, R., Hong, T.H., Herman, M. and Luck, R.

"Analysis of Optical Flow Estimation Using Epipolar Plane Images," NISTIR 4569, Gaithersburg, MD, April 1991

Rangachar, R., Hong, T.H., Herman, M. and Luck, R.

"Three Dimensional Reconstruction From Optical Flow Using Temporal Integration," NISTIR 4570, Gaithersburg, MD, April 1991

RAVIV, Daniel

Raviv, D.

"Quantitative Approach to Camera Fixation," NISTIR 4324, Gaithersburg, MD, May 1990

Raviv, D. and Herman, M.

"Towards an Understanding of Camera Fixation," Proceedings of the IEEE International Conference on Robotics and Automation, Cincinnati, OH, May 1990

Yakali, H.H., Raviv, D. and Herman, M.

"Integrated Mobile Robot System for Testing Vision Algorithms," Proceedings of the 3rd Conference on Recent Advances in Robotics, Florida Atlantic University, Boca Raton, FL, July 2-3, 1990

Raviv, D. and Albus, J.S.

"Closed-form Massively-Parallel Range-from-Image Flow Algorithm," NISTIR 4450, Gaithersburg, MD, October 1990

Raviv, D.

"Reconstruction During Camera Fixation," SPIE Symposium on Intelligent Robots and Computer Vision, Boston, MA, November 1990

Yakali, H.H., Raviv, D. and Herman, M.

"Road Following -- Á New Approach," Proceedings of the Fourth Annual Conference on Recent Advances in Robotics, Boca Raton, FL, May 1991

Raviv, D. and Albus, J.S.

"Image-Flow Based Reconstruction Algorithm (Extracted from "Closed-Form Massively Parallel Range from Image Flow Algorithm")," Proceedings of the Fourth Annual Conference on Recent Advances in Robotics, Florida High-Technology and Industrial Council, Boca Raton, FL, May 16-17, 1991

Raviv, D. and Herman, M.

"Visual Control Signals for Road Following," Proceedings of the 1991 IEEE International Symposium on Intelligent Control, Arlington, VA, August 1991

Raviv. D.

"An Integration-Based Method for Depth Estimation," NISTIR 4669, Gaithersburg, MD, September 1991

Raviv, D. and Herman, M.

"A New Approach to Vision-Based Road Following for Autonomous Vehicles," Proceedings of the IEEE International Conference on Systems, Man & Cybernetics, Charlottesville, VA and Proceedings of the IEEE Workshop on Visual Motion, Princeton, NJ, October 1991 Raviv, D. and Herman, M.

"A New Approach to Vision and Control for Road Following," NISTIR 4476, Gaithersburg, MD, January 1991 & Proceedings of the IEEE Workshop on Visual Motion, Princeton, NJ, October 7-9, 1991

Raviv, D.

"Invariants in Visual Motion," NISTIR 4722, Gaithersburg, MD, November 1991

Raviv, D. and Herman, M.

"A "Nonreconstruction" Approach for Road Following," Proceedings of the SPIE Conference on Intelligent Robots and Computer Vision X, Boston, MA, November 1991

Yakali, H.H., Raviv, D. and Herman, M.

"New Vision-Based Approach for Navigation," Proceedings of the SPIE Advances in Intelligent Robotics Systems: Mobile Robots VI, Vol. 1613, Boston, MA, November 1991

Raviv, D. and Albus, J.S.

"Representations in Visual Motion," NISTIR 4747, Gaithersburg, MD, January 1992

Raviv, D.

"Flat Surfaces: A Visual Invariant," NISTIR 4794, Gaithersburg, MD, March 1992

Raviv, D., Orser, D. and Albus, J.S.

"On Logarithmic Retinae," NISTIR 4807, Gaithersburg, MD, April 1992

Raviv, D.

"A Quantitative Approach to Looming," NISTIR 4808, Gaithersburg, MD, April 1992

Raviv, D. and Albus, J.S.

"A Closed-Form Massively-Parallel Range-From-Image-Flow Algorithm," Proceedings of the IEEE Transactions on Systems, Man and Cybernetics, Vol. 22, No. 2, March/April 1992

Raviv, D. and Herman, M.

"Visual Servoing for Robot Vehicles Using Relevant 2-D Image Cues," NISTIR 4921, Gaithersburg, MD, September 1992

Raviv, D.

"Visual Looming," Proceedings of the SPIE Conference on Intelligent Robots and Computer Vision, Boston, MA November 1992

Joarder, K. and Raviv, D.

"Autonomous Obstacle Avoidance Using Visual Fixation and Looming," NISTIR 4996, Gaithersburg, MD, December 1992

Raviv, D. and Herman, M.

"Visual Servoing Using Relevant 2-D Image Cues," Proceedings of the Intelligent Vehicles '93 Conference, Tokyo, Japan, July 14-16, 1993

Herman, M., Raviv, D., Schneiderman, H. and Nashman, M.

"Visual Road Following Without 3-D Reconstruction," Proceedings of the SPIE 22nd Applied Imagery Pattern Recognition Workshop, Vol. 2103, Washington, DC, October 1993

RICHARDSON, B.S.

Corbett, G.K., Killough, S.M., Richardson, B.S. and Herman, M.

"Human Factors Testbed for Ground-Vehicle Telerobotics Research," Proceedings of the IEEE Southeast Conference '90, New Orleans, LA, April 1-4, 1990

RIPPEY, William G.

Rippey, W.G.

"Integration Testing of the AMRF," Proceedings of the Second International Conference on Flexible Automation & Information Management, FAIM 92, Falls Church, VA, June 29-July 2, 1992

Rippey, W.G.

"The NIST MTC's CAD/CAM Selection Tool," Proceedings of the AUTOFACT '92 Conference, Detroit, MI, November 1992

ROBERTS, Karen J.

Wavering, A.J., Fiala, J.C., Roberts, K.J. and Lumia, R.

"TRICLOPS: A High-Performance Trinocular Active Vision System," Proceedings of the IEEE Conference on Robotics and Automation, Atlanta, GA, May 2-6, 1993

Fiala, J.C., Lumia, R., Roberts, K.J. and Wavering, A.J.

"TRICLOPS: A Tool for Studying Active Vision," Submitted to International Journal of Computer Vision

ROCHE, Martin

Roche, M.

"Geometric Elements for Pipe Routing Using a Computer," Civil Engineering for Practicing and Design Engineers, Vol. 5, pgs 975-984, November 1986

Orser, D.J. and Roche, M.

"Extraction of Topographic Features in Support of Autonomous Underwater Vehicle Navigation," Proceedings of Fifth International Symposium of Unmanned, Untethered, Submersible Technology, Merrimack, NH, June 22-24, 1987

Roche, M. and Beusan, S.

"Using Available Curve-Shaped Information with a Non-Uniform B-Spline," Computers in Mechanical Engineering, Vol. 5, No. 7, pgs 63-69, July 1987

Roche, M. and Li, W.X.

"Note on Real Time Parametric Cubic Segment Curve Generation," Intelligent Instruments and Computers, Vol. 5, No. 7, pgs 168-174, July 1987

Roche, M. and Li. W.

"Real Time Generation of Smooth Curves using Local Cubic Segments," ACCESS, Vol. 7, No. 6, November 1988

Albus, J.S., Quintero, R., Huang, H.M. and Roche, M.

"Mining Automation Real-Time Control System Architecture Standard Reference Model (MASREM)," NISTTN 1261, Volume 1, Gaithersburg, MD, May 1989

ROSOL, Mark

Herman, M., Hong, T.H., Swetz, S., Oskard, D. and Rosol, M.

"Planning and World Modeling for Autonomous Undersea Vehicles," Proceedings of the Third IEEE International Symposium on Intelligent Control, Arlington, VA, August 24-26, 1988

ROWE, Walter P.

Manheimer, K.L., Clark, S.N., Warsaw, B.A. and Rowe, W.P.

"The Depot: A Framework for Sharing Software Installation Across Organizational and UNIX Platform Boundaries," NISTIR 4436, Gaithersburg, MD, September 1990

RUSSELL, Robert T.

Proctor, F.M. and Russell, R.

"Inventory of Equipment in the Cleaning and Deburring Workstation," NISTIR 89-4092, Gaithersburg, MD, May 1989

Proctor, F.M. and Russell, R.

"Recommended Technical Specifications for Procurement of Systems for a Cleaning and Deburring Workstation," NISTIR 89-4115, Gaithersburg, MD, June 1989

Russell, R.T.

"Inventory in the Advanced Deburring and Chamfering System," NISTIR 4932, Gaithersburg, MD, September 1992

Stouffer, K., Michaloski, J., Russell, R. and Proctor, F.

"ADACS - An Automated System for Part Finishing," NISTIR 5171, Gaithersburg, MD, April 1993

RUTOWSKI, W.S.

Shneier, M.O., Rutowski, W.S. and Hong, T.H.

"Using Chebyshev Polynomials for Interpreting Structured Light Images," Proceedings of the IEEE International Conference on Robotics and Automation, April 1985

SAUDER, David A.

Kramer, T.R., Morris, K.C. and Sauder, D.A.

"A Structural EXPRESS Editor," NISTIR 4903, Gaithersburg, MD, August, 1992

SCHNEIDERMAN, Henry W.

Schneiderman, H. and Nashman M.

"Visual Processing for Autonomous Driving," Proceedings of the IEEE Workshop on Applications of Computer Vision, Palm Spring, CA, November 30-December 2, 1992

Schneiderman, H. and Albus, J.S.

"Progress and Prospects for Vision-Based Automatic Driving," Proceedings of the IVHS America '93 Conference, Washington, DC, April 14-17, 1993

Nashman, M. and Schneiderman, H.

"Real-Time Visual Processing for Autonomous Driving," Proceedings of the IEEE Intelligent Vehicles '93 Conference, Tokyo, Japan, July 14-16, 1993

Murphy, K., Juberts, M., Legowik, S., Nashman, M., Schneiderman, H., Scott, H. and Szabo, S.

"Ground Vehicle Control at NIST: from Teleoperation to Autonomy," Published at the Seventh Annual Space Operations, Applications, and Research Symposium, Houston, TX, August 3-5, 1993

Schneiderman, H., Nashman, M. and Lumia, R.

"Model-based vision for car following," Proceedings of the SPIE Sensor Fusion VI, Boston, MA, September 1993

Juberts, M., Murphy, K., Nashman, M., Scheiderman, H., Scott, H. and Szabo, S. "Development and Test Results for a Vision-Based Approach to AVCS," Proceedings of the 26th International Symposium on Automotive Technology and Automation, Aachen, Germany,

September 1993

Herman, M., Raviv, D., Schneiderman, H. and Nashman, M.

"Visual Road Following Without 3-D Reconstruction," Proceedings of the SPIE 22nd Applied Imagery Pattern Recognition Workshop, Vol. 2103, Washington, DC, October 1993

Schneiderman, H. and Nashman, M.

"Visual Tracking for Autonomous Driving," To be published in IEEE Transactions on Robotics and Automation

SCOTT, Harry A.

Albus, J.S., Barbera, A.J., Fitzgerald, M.L., Kent, E.W., **Scott, H.A.** and Kilmer, R.D. "A Control System for an Automated Manufacturing Research Facility," Proceedings of the Robots 8 Conference and Exposition, Volume 2 - Future Considerations, Detroit, MI, June 4-7, 1984

Scott, H. and Strouse, K.

"Workstation Control in a Computer Integrated Manufacturing System," Proceedings of the Autofact 6, Anaheim, CA, October 1984

Szabo, S., Scott, H.A. and Kilmer, R.D.

"Control System Architecture for the Team Program," Proceedings of the Second International Symposium on Robotics and Manufacturing Research Education and Applications, Alburqurque, NM, November 16-18, 1988

Szabo, S., Scott, H.A. and Kilmer, R.D.

"Control System Architecture for Unmanned Ground Vehicles," Proceedings of the AUVS-90, Dayton, OH, July 30-August 1, 1990

Szabo, S., Scott, H.A., Murphy, K.N. and Legowik, S.A.

"Control System Architecture for a Remotely Operated Unmanned Land Vehicle," Proceedings of the 5th IEEE International Symposium on Intelligent Control, Philadelphia, PA, September 1990

Scott, H.

"Vehicle-Command Center Communications in a Robotic Vehicle System," International Journal of Robotics and Autonomous Systems, October 1990

Szabo, S., Murphy, K.N., **Scott, H.A.**, Legowik, S.A. and Bostelman, R.V. "Control System Architecture for Unmanned Land Vehicles," Proceedings of the Association for Unmanned Vehicle Systems, Huntsville, AL, June 21-24, 1992

Szabo, S., **Scott, H.A.**, Murphy, K.N., Legowik, S.A. and Bostelman, R.V. "High-Level Mobility Controller for a Remotely Operated Unmanned Land Vehicle," Journal of Intelligent and Robotic System, Vol. 5, pgs 63-77, 1992

Murphy, K., Juberts, M., Legowik, S., Nashman, M., Schneiderman, H., Scott, H. and Szabo, S.

"Ground Vehicle Control at NIST: from Teleoperation to Autonomy," Published at the Seventh Annual Space Operations, Applications, and Research Symposium, Houston, TX, August 3-5, 1993

Herman, M., Szabo, S., Murphy, K., Coombs, D., Hong, T.H., **Scott**, **H.** and Dagalakis, N. "Recommendations for Performance Evaluation of Unmanned Ground Vehicle Technologies," NISTIR 5244, Gaithersburg, MD, August 1993

Juberts, M., Murphy, K., Nashman, M., Scheiderman, H., **Scott, H.** and Szabo, S. "Development and Test Results for a Vision-Based Approach to AVCS," Proceedings of the 26th International Symposium on Automotive Technology and Automation, Aachen, Germany, September 1993

SENEHI, M.K.

Kramer, T.R. and Senehi, M.K.

"Feasibility Study: Reference Architecture for Machine Control Systems Integration," NISTIR 5297, Gaithersburg, MD, November 1993

SHAFFER, C.A.

Oskard, D.N., Hong, T.H. and Shaffer, C.A.

"Real-Time Algorithms and Data Structures for Underwater Mapping," Proceedings of the SPIE Advances in Intelligent Robotics Systems Conference, Boston, MA, November 10-11, 1988

SHNEIER, Michael O.

Shneier, M., Nagalia, S., Albus, J.S. and Haar, R.

"Visual Feedback for Robot Control," Proceedings of the International Workshop on Industrial Applications of Machine Vision, Research Triangle, NC, May 3-5, 1982

Albus, J.S., Kent, E., Nashman, M., Mansbach, P., Palombo, L. and **Shneier**, **M.O.** "Six-Dimensional Vision System." SPIE Vol. 336 Robot Vision, May 1982

Shneier, M.O., Kent, E.W. and Mansbach, P.

"Representing Workspace and Model Knowledge for a Robot with Mobile Sensors," Proceedings of the 7th International Conference on Pattern Recognition, Montreal, Canada, July 1984

Kent, E.W., Shneier, M.O., Lumia, R., Herriman, M., Luck, R.L. and Henrici, G.S. "Architecture of the NBS Pipelined Image Processing Engine," Conference on Algorithm-Guide

Parallel Architectures for Automatic Target Recognition, Leesburg, VA, 1984

Lumia, R., Shneier, M.O. and Kent, E.W.

"Real-Time Iconic Image Processor," Proceedings of the IEEE International Conference on Robotics and Automation, St. Louis, MO, March 1985

Shneier, M.O., Rutowski, W.S. and Hong, T.H.

"Using Chebyshev Polynomials for Interpreting Structured Light Images," Proceedings of the IEEE International Conference on Robotics and Automation, April 1985

Hong, T.H. and Shneier, M.O.

"Describing a Robot's Workspace using a Sequence of Views from a Moving Camera," IEEE Transactions on Pattern Analysis and Machine Intelligence, Vol. PAMI-7, No. 6, November 1985

Kent, E.W., Shneier, M.O. and Lumia, R.

"Pipe," Journal of Parallel and Distributed Computing, 1985

Shneier, M.O., Lumia, R. and Kent, E.W.

"Model-Based Strategies for High-Level Robot Vision," Computer Vision, Graphics and Image Processing, pgs 293-306, March 1986

Kent, E.W., Shneier, M.O. and Hong, T.H.

"Building Representations From Fusion of Multiple Views," Proceedings of the IEEE International Conference on Robotics and Automation, San Francisco, CA, April 7-10, 1986

Hong, T.H. and Shneier, M.O.

"Rotation and Translation of Objects Represented by Octrees," Proceedings of the International Conference on Pattern Recognition, Paris, France, 1986

Shneier, M.O., Lumia, R. and Herman, M.

"Prediction-Based Vision for Robot Control," Computer Magazine, pgs 46-55, February 1987

Mansbach, P. and Shneier, M.

"Gramps Operating System: User's Guide," NBSIR 88-3778, Gaithersburg, MD, September 1988

SIEWERT, Thomas

Hira, R., Quintero, R., Goodwin, K. and Siewert, T.

"Report on Mobility for Welding Automation in Ship Construction," NISTIR 5301, Gaithersburg, MD, December 1993

SIMPSON, John A.

Simpson, J.A., Hocken, R.J. and Albus, J.S.

"Automated Manufacturing Research Facility of the National Bureau of Standards," Journal of Manufacturing Systems: Society of Manufacturing Engineers, 1(1): pgs 17-32, 1982

SMITH, Bradford M.

Smith, B.M., Albus, J.S. and Barbera, A.J.

"A Glossary of Terms for Robotics," NBSIR 81-2340, Gaithersburg, MD, October 1981

STOUFFER, Keith A.

Stouffer, K.A.

"Development of the Forward and Inverse Kinematic Models for the Advanced Deburring and Chamfering System (ADACS) Industrial Robot," NISTIR 4928, Gaithersburg, MD, September 1992

Stouffer, K., Michaloski, J., Russell, R. and Proctor, F.

"ADACS - An Automated System for Part Finishing," NISTIR 5171, Gaithersburg, MD, April 1993

Stouffer, K.

"NIST Integrated CAD into Robotic Chamfering," To be published in a future issue of CADENCE Magazine

STROUSE, K.

Scott, H. and Strouse, K.

"Workstation Control in a Computer Integrated Manufacturing System," Proceedings of the Autofact 6, Anaheim, CA, October 1984

SWETZ, Scott

Herman, M., Hong, T.H., Swetz, S., Oskard, D. and Rosol, M.

"Planning and World Modeling for Autonomous Undersea Vehicles," Proceedings of the Third IEEE International Symposium on Intelligent Control, Arlington, VA, August 24-26, 1988

SWYT, Dennis A.

Swyt, D.A.

"AI in Manufacturing: The NBS AMRF as an Intelligent Machine," Proceedings of the International Conference on Expert Systems in Production Planning and Control, Charleston, SC, May 1987

SZABO, Sandor

Szabo, Ś., Juberts, M. and Kilmer, R.D.

"Automated Guided Vehicles at the National Bureau of Standards Automatic Manufacturing Research Facilty," Journal of Unmanned Vehicle Systems, pgs 38-47, Summer 1984

McCain, H.G., Kilmer, R.D., Szabo, S. and Abrishamian, A.

"Hierarchically Controlled Autonomous Robot for Heavy Payload Military Field Applications," Proceedings of the International Conference on Intelligent Autonomous Systems, Amsterdam, The Netherlands, December 1986

Szabo, S., Scott, H.A. and Kilmer, R.D.

"Control System Architecture for the Team Program," Proceedings of the Second International Symposium on Robotics and Manufacturing Research Education and Applications, Alburqurque, NM, November 16-18, 1988

Szabo, S., Scott, H.A. and Kilmer, R.D.

"Control System Architecture for Unmanned Ground Vehicles," Proceedings of the AUVS-90, Dayton, OH, July 30-August 1, 1990

Szabo, S., Scott, H.A., Murphy, K.N. and Legowik, S.A.

"Control System Architecture for a Remotely Operated Unmanned Land Vehicle," Proceedings of the 5th IEEE International Symposium on Intelligent Control, Philadelphia, PA, September 1990

Albus, J.S., Juberts, M. and Szabo, S.

"RCS: A Reference Model Architecture for Intelligent Vehicle and Highway Systems," Proceedings of the 25th Silver Jubilee International Symposium on Automotive Technology and Automation, Florence, Italy, June 1-5, 1992

Szabo, S., Murphy, K.N., Scott, H.A., Legowik, S.A. and Bostelman, R.V. "Control System Architecture for Unmanned Land Vehicles," Proceedings of the Association for Unmanned Vehicle Systems, Huntsville, AL, June 21-24, 1992

Szabo, S., Scott, H.A., Murphy, K.N., Legowik, S.A. and Bostelman, R.V. "High-Level Mobility Controller for a Remotely Operated Unmanned Land Vehicle," Journal of Intelligent and Robotic System, Vol. 5, pgs 63-77, 1992

Murphy, K., Juberts, M., Legowik, S., Nashman, M., Schneiderman, H., Scott, H. and Szabo, S.

"Ground Vehicle Control at NIST: from Teleoperation to Autonomy," Published at the Seventh Annual Space Operations, Applications, and Research Symposium, Houston, TX, August 3-5, 1993

Herman, M., Szabo, S., Murphy, K., Coombs, D., Hong, T.H., Scott, H. and Dagalakis, N. "Recommendations for Performance Evaluation of Unmanned Ground Vehicle Technologies," NISTIR 5244, Gaithersburg, MD, August 1993

Juberts, M., Murphy, K., Nashman, M., Scheiderman, H., Scott, H. and **Szabo**, **S.** "Development and Test Results for a Vision-Based Approach to AVCS," Proceedings of the 26th International Symposium on Automotive Technology and Automation, Aachen, Germany, September 1993

TANGUY, Peter S.

Murphy, K.N., Tanguy, P.S., Norcross, R. and Proctor, F.

"Cleaning and Deburring Workstation Operations Manual," NBSIR 88-3804, Gaithersburg, MD, June 1988

Proctor, F.M. and Tanguy, P.S.

"CAD Directed Automated Part Handling User's Reference Manual," NISTIR 88-3858, Gaithersburg, MD, September 1988

TANIMOTO, S.L.

Kent, E.W. and Tanimoto, S.L.

"Hierarchical Cellular Logic and the Pipe Processor: Structural and Functional Correspondence," IEEE Computer Society Workshop on Computer Architecture for Pattern Analysis and Image Database Management - Capaidm, Miami Beach, FL, July 1985

TARNOFF, Nicholas

Tarnoff, N. and Lumia, R.

"Role of Off-Line Robot Programming in Hierarchical Control," Proceedings of the Second International Symposium Robotics and Manufacturing Research, Education, and Applications, Albuquerque, NM, November 16-18, 1988

Tarnoff, N., Jacoff, A. and Lumia, R.

"World Model Registration for Effective Off-Line Programming of Robots," Proceedings of the IEEE Third International Symposium on Robotics and Manufacturing (ISRAM 90), Burnaby, British Columbia, Canada, July 18-20, 1990

Albus, J.S., Quintero, R., Proctor, F., Michaloski, J., Dagalakis, N. and **Tarnoff, N.** "NIST Support to the Next Generation Controller Program: 1991 Final Technical Report," NISTIR 4888, Gaithersburg, MD, August 1992

Tarnoff, N., Jacoff, A. and Lumia, R.

"Graphical Simulation for Sensor-Based Robot Programming," Journal of Intelligent and Robotic Systems, Vol. 5, pgs 49-62, 1992

TCHORYK, Peter

Quintero, R., Montgomery, R.C. and Tchoryk, P.

"Autonomous Rendezvous and Docking Scenarios for the Development of Guidelines and Standards," Proceedings of the AIAA Space Programs and Technologies Conference and Exhibit, Huntsville, AL, September 21-23, 1993

TSAI, Tsung-Ming

Lee, J.D., Haynes, L.S., Wang, B.L. and Tsai, T.M.

"Control of Flexible Robot Arm," Modelings and Control of Robotic Manipulators and Manufacturing Processes, SME, pgs 241-251, 1987

Lee, J.D., Albus, J.S., Dagalakis, N.G. and Tsai, T.M.

"Computer Simulation of a Parallel Link Manipulator," Robotics and Computer Integrated Manufacturing, August 1988

Unger, J., Dagalakis, N.G., Tsai, T.M. and Lee, J.D.

"Optimum Stiffness Study for a Parallel Link Robot Crane under Horizontal Force," Proceedings of the Second International Symposium on Robotics and Manufacturing Research, Education, and Applications, Albuquerque, NM, November 16-18,1988

Lee, J.D., Albus, J.S., Dagalakis, N.G. and Tsai, T.M.

"Performance Measures of a Robotic Micropositioner," Proceedings of the 2nd International Symposium on Robotics and Manufacturing ASME, pgs 1047-1056, 1988

Dagalakis, N.G., Albus, J.S., Goodwin, K.R., Lee, J.D., Tsai, T.M., Abrishamian, A., Bostelman, R. and Yancey, C.

"Robot Crane Technology (Final Report)," NISTTN 1267, Gaithersburg, MD, July 1989

Bostelman, R., Albus, J., Murphy, K., Tsai, T. and Amatucci, E.

"A Stewart Platform Lunar Rover," Proceedings of the Space '94 Conference, Albuquerque, NM, February 28 - March 3, 1994

UNGER, Joseph

Dagalakis, N.G., Albus, J.S., Wang, B.L., Unger, J. and Lee, J.D.

"Stiffness Study of a Parallel Link Robot Crane for Shipbuilding Applications," Proceedings of the 7th International Conference for Offshore Mechanical and Arctic Engineering, Houston, TX, February 7-12, 1988

Albus, J.S., Dagalakis, N.G., Wang, B.L., Unger, J., Lee, J.D. and Yancey, C.W.

"Available Robotics Technology for Applications in Heavy Industry," 1988 Iron and Steel Exposition and Annual Convention, Houston, TX, February 7-12, 1988

Unger, J., Dagalakis, N.G., Tsai, T.M. and Lee, J.D.

"Optimum Stiffness Study for a Parallel Link Robot Crane under Horizontal Force," Proceedings of the Second International Symposium on Robotics and Manufacturing Research, Education, and Applications, Albuquerque, NM, November 16-18, 1988

UZZAMAN, S.

Albus, J., Meystel, A. and Uzzaman, S.

"Nested Motion Planning for an Autonomous Robot," Proceedings of the IEEE Regional Conference on Aerospace Control Systems, Westlake Village, CA, May 25-27, 1993

VANDERBRUG, Gordon J.

VanderBrug, G.J., Albus, J.S. and Barkmeyer, E.

"A Vision System for Real-Time Control of Robots," Proceedings of the 9th International Symposium on Industrial Robots, Washington, DC, March 13-15, 1979

Nagel, R.N., VanderBrug, G.J., Albus, J.S. and Lowenfeld, E.

"Experiments In Part Acquisition Using Robot Vision," Proceedings of the Autofact II, Robots IV Conference, Detroit, MI, October 29 - November 1, 1979

Albus, J.S., Barbera, A., Fitzgerald, M.L., Nagel, R., VanderBrug, G. and Wheatley, T.E. "A Measurement and Control Model for Adaptive Robots," Proceedings of the 10th International Symposium on Industrial Robots, Milan, Italy, March 1980

WALKER, Ellen L.

Walker, E.L., Herman, M. and Kanade, T.

"Framework for Representing and Reasoning about Three-Dimensional Objects for Vision," AI Magazine, Vol. 9, No. 2. pgs 47-58, October 1987

Walker, E.L. and Herman, M.

"Geometric Reasoning for Constructing 3D Scene Descriptions from Images" Artificial Intelligence, Vol. 37, No. 1-3, pgs 275-290, December 1988

WANG, Ben-Li

Lee, J.D., Haynes, L.S., Wang, B.L. and Tsai, T.M.

"Control of Flexible Robot Arm," Modelings and Control of Robotic Manipulators and Manufacturing Processes, SME, pgs 241-251, 1987

Dagalakis, N.G., Albus, J.S., Wang, B.L., Unger, J. and Lee, J.D.

"Stiffness Study of a Parallel Link Robot Crane for Shipbuilding Applications," Proceedings of the 7th International Conference for Offshore Mechanical and Arctic Engineering, Houston, TX, February 7-12, 1988

Albus, J.S., Dagalakis, N.G., Wang, B.L., Unger, J., Lee, J.D. and Yancey, C.W.

"Available Robotics Technology for Applications in Heavy Industry," 1988 Iron and Steel Exposition and Annual Convention, Houston, TX, February 7-12, 1988

Lee, J.D. and Wang, B.L.

"Optimal Control of a Flexible Robot Arm," Computers and Structures, Vol. 29, No. 3, pgs 459-467, 1988

Lee, J.D. and Wang, B.L.

"Dynamic Equations for a Two-Link Flexible Robot Arm," Computers and Structures, Vol. 29, No. 3, pgs 469-477, 1988

WARSAW, Barry A.

Michaloski, J.L. and Warsaw, B.A.

"Robot Control System Based on Forth," Robotics Engineering, Vol. 8, No. 5, pgs 22-26, May 1986

Manheimer, K.L., Clark, S.N., Warsaw, B.A. and Rowe, W.P.

"The Depot: A Framework for Sharing Software Installation Across Organizational and UNIX Platform Boundaries," NISTIR 4436, Gaithersburg, MD, September 1990

Warsaw, B. and Michaloski, J.

"The TROI [Telerobotic Operator Interface] User's Guide," NISTIR 4471, Gaithersburg, MD, January 1991

Michaloski, J.L. and Warsaw, B.

"TROI Real-Time Operator Interface Management System for the NASREM Architecture," Proceedings of the 4th Topical Meeting on Robotics and Remote Systems, February 1991

WAVERING, Albert J.

Fiala, J.C. and Wavering, A.J.

"RCS Application Example: Tool Changing on a Horizontal Machining Center," Proceedings of the Second International Conference on Robotics and Factories of the Future, San Diego, CA, July 28-31, 1987

Wavering, A.J. and Fiala, J.C.

"Real-Time Control System of the Horizontal Workstation Robot," NBSIR 88-3692, Gaithersburg, MD, December 1987

Lumia, R., Fiala, J.C. and Wavering, A.J.

"Architecture to Support Autonomy, Teleoperation, and Shared Control," Proceedings of the IEEE Conference on Systems, Man, and Cybernetics, Beijing, China, August 5-10, 1988

Wavering, A.J.

"Manipulator Primitive Level Task Decompostion," NISTTN 1256, Gaithersburg, MD, September 1988

Lumia, R., Fiala, J. and Wavering, A.

"NASREM: Robot Control System and Testbed," Proceedings of the Second International Symposium on Robotics and Manufacturing Research, Education, and Applications, Alburquerque, NM, November 16-18, 1988

Lumia, R. and Wavering, A.J.

"Trajectory Generation for Space Telerobots," Proceedings of the 1989 Conference on Space Telerobotics, Pasadena, CA, January 31 - February 2, 1989

Albus, J.S., Lumia, R., Fiala, J. and Wavering, A.

"NASREM -- The NASA/NBS Standard Reference Model for Telerobot Control System Architecture," Proceedings of the 20th International Symposium on Industrial Robots, Tokyo, Japan, October 4-6, 1989

Lumia, R., Fiala, J.C. and Wavering, A.J.

"NASREM Robot Control System Standard," Robotics & Computer-Integrated Manufacturing, Vol. 6, No. 4, pgs 303-308, November 1989

Fiala, J.C. and Wavering, A.J.

"Implementation of a Jacobian-Transpose Algorithm," NISTIR 90-4286, Gaithersburg, MD, April 1990

Dagalakis, N.G. and Wavering, A.J.

"Recommended Fine Positioning Test for the Development Test Flight (DTF-1) of the NASA Flight Telerobotic Servicer (FTS)," NISTIR 4478, Gaithersburg, MD, December 1990

Fiala, J., Wavering, A. and Lumia, R.

"A Manipulator Control Testbed: Implementation and Applications," Proceedings of the 15th Annual AAS Guidance and Control Conference, Keystone, CO, February 8-12, 1992

Fiala, J. and Wavering, A.

"Experimental Evaluation of Cartesian Stiffness Control on a Seven Degree-of-Freedom Robot Arm," Journal of Intelligent and Robotic Systems, Vol. 5, pgs 5-24, 1992

Wavering, A.J., Fiala, J.C., Roberts, K.J. and Lumia, R.

"TRICLOPS: A High-Performance Trinocular Active Vision System," Proceedings of the IEEE Conference on Robotics and Automation, Atlanta, GA, May 2-6, 1993

Wavering, A.J. and Lumia, R.

"Predictive visual tracking," Proceedings of the SPIE Intelligent Robots and Computer Vision XII, Boston, MA, September 7-10, 1993

Fiala, J.C., Lumia, R., Roberts, K.J. and Wavering, A.J.

"TRICLOPS: A Tool for Studying Active Vision," Submitted to International Journal of Computer Vision

WHEATLEY, Thomas E.

Albus, J.S., Barbera, A., Fitzgerald, M.L., Nagel, R., VanderBrug, G. and Wheatley, T.E. "A Measurement and Control Model for Adaptive Robots," Proceedings of the 10th International Symposium on Industrial Robots, Milan, Italy, March 1980

Kent, E.W., Wheatley, T.E. and Nashman, M.

"Real-Time Cooperative Interaction between Structured-Light and Reflectance Ranging for Robot Guidance," Robotica, Volume 3, pgs 7-11, 1985

Michaloski, J.L., Wheatley, T.E. and Lumia, R.

"Exploiting Computational Parallelism with a Hierarchical Robot Control System," IEEE Journal of Robotics and Automation, April 1988

Michaloski, J.L., Lumia, R. and Wheatley, T.E.

"Heuristics for Robot System Design Using a Concurrent Hierarchical Control Model," Robot Systems Division Internal Report, National Institute of Standards and Technology, Gaithersburg, MD, September 1988

Wheatley, T.E.

"Mapping Processes to Processors for Space Based Robot Systems," Proceedings of the IEEE International Conference on Systems Engineering, Wright State University, Dayton, OH, August 24-26, 1989

Michaloski, J.L., Wheatley, T.E. and Lumia, R.

"Analysis of Computational Parallelism with a Concurrent Hierarchical Robot Control System," NISTIR 90-4251, Gaithersburg, MD, March 1990

Wheatley, T.E. and Michaloski, J.

"Configuration and Performance Evaluation of a Real-Time Robot Control System: The Skeleton Approach," Proceedings of the IEEE International Conference on Systems Engineering, Pittsburgh, PA, August 1990

Michaloski, J. and Wheatley, T.

"System Factors in Real-Time Hierarchical Control," NISTIR 4386, Gaithersburg, MD, August 1990

Michaloski, J. and Wheatley, T.

"Design Principles for a Real-Time Robot Control System," Proceedings of the IEEE International Conference on Systems Engineering, Pittsburgh, PA, August 1990

Wheatley, T.E.

"Determining Bus Arbitration Policies and Data Transfer Techniques for Multiprocessor Systems," Proceedings of the IEEE International Conference on Systems Engineering, Dayton, OH, August 1991

YAKALI, H.H.

Yakali, H.H., Raviv, D. and Herman, M.

"Integrated Mobile Robot System for Testing Vision Algorithms," Proceedings of the 3rd Conference on Recent Advances in Robotics, Florida Atlantic University, Boca Raton, FL, July 2-3, 1990

Yakali, H.H., Raviv, D. and Herman, M.

"Road Following -- A New Approach," Proceedings of the Fourth Annual Conference on Recent Advances in Robotics, Boca Raton, FL, May 1991

Yakali, H.H., Raviv, D. and Herman, M.

"New Vision-Based Approach for Navigation," Proceedings of the SPIE Advances in Intelligent Robotics Systems: Mobile Robots VI, Vol. 1613, Boston, MA, November 1991

YANCEY, Charles W.

Albus, J.S., Dagalakis, N.G., Wang, B.L., Unger, J., Lee, J.D. and Yancey, C.W. "Available Robotics Technology for Applications in Heavy Industry," 1988 Iron and Steel Exposition and Annual Convention, Houston, TX, February 7-12, 1988

Dagalakis, N.G., Albus, J.S., Goodwin, K.R., Lee, J.D., Tsai, T.M., Abrishamian, A., Bostelman, R. and Yancey, C.

"Robot Crane Technology (Final Report)," NISTTN 1267, Gaithersburg, MD, July 1989

YANG, Charles

Proctor, F.M., Damazo, B., Yang, C. and Frechette, S.

"Open Architectures for Machine Control," NISTIR 5307, Gaithersburg, MD, December 1993

YANG, Jackson C.S.

Young, G.S., Hong, T.H., Herman, M. and Yang, J.C.S.

"Kinematic Calibration of an Active Camera System," NISTIR 4715, Gaithersburg, MD, November 1991

Young, G.S., Hong, T.H., Herman, M. and Yang, J.C.S.

"Kinematic Calibration of an Active Camera System," Proceedings of the 1992 IEEE Computer Society Conference on Computer Vision and Pattern Recognition, Champaign, IL, June 15-18, 1992

Young, G.S., Hong, T.H., Herman, M. and Yang, J.C.S.

"Obstacle Detection and Terrain Characterization Using Optical Flow Without 3-D Reconstruction," Proceedings of the SPIE 1825 on Intelligent Robots and Computer Vision XI, Boston, MA, November 16-18, 1992

Young, G.S., Hong, T.H., Herman, M. and Yang, J.C.S.

"New Visual Invariants for Obstacle Detection Using Optical Flow Induced From General Motion," Proceedings of the IEEE Workshop on Applications of Computer Vision, Palm Spring, CA, November 30-December 2, 1992

Young, G.S., Hong, T.H., Herman, M. and Yang, J.C.S.

"Safe Navigation for Autonomous Vehicles: A Purposive and Direct Solution," Proceedings of the SPIE Conference on Intelligent Robots and Computer Vision XII: Active Vision and 3D Methods, Boston, MA, September 1993

YOUNG, Gin-Shu

Young, G.S., Hong, T.H., Herman, M. and Yang, J.C.S.

"Kinematic Calibration of an Active Camera System," NISTIR 4715, Gaithersburg, MD, November 1991

Young, G.S., Hong, T.H., Herman, M. and Yang, J.C.S.

"Kinematic Calibration of an Active Camera System," Proceedings of the 1992 IEEE Computer Society Conference on Computer Vision and Pattern Recognition, Champaign, IL, June 15-18, 1992

Young, G.S., Hong, T.H. and Herman, M.

"Obstacle Detection for a Vehicle Using Optical Flow," Proceedings of the Intelligent Vehicles '92 Conference, Detroit, MI, June 29 - July 1, 1992

Young, G.S., Hong, T.H., Herman, M. and Yang, J.C.S.

"Obstacle Detection and Terrain Characterization Using Optical Flow Without 3-D Reconstruction," Proceedings of the SPIE 1825 on Intelligent Robots and Computer Vision XI, Boston, MA, November 16-18, 1992

Young, G.S., Hong, T.H., Herman, M. and Yang, J.C.S.

"New Visual Invariants for Obstacle Detection Using Optical Flow Induced From General Motion," Proceedings of the IEEE Workshop on Applications of Computer Vision, Palm Spring, CA, November 30-December 2, 1992

Young, G.S., Hong, T.H., Herman, M. and Yang, J.C.S.

"Safe Navigation for Autonomous Vehicles: A Purposive and Direct Solution," Proceedings of the SPIE Conference on Intelligent Robots and Computer Vision XII: Active Vision and 3D Methods, Boston, MA, September 1993

